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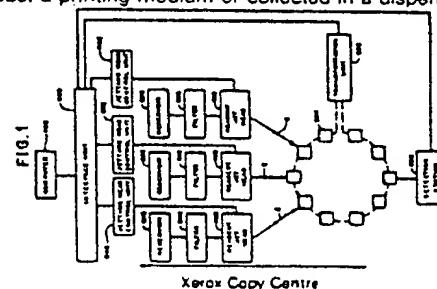
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④ Apparatus and process for reagent fluid dispensing and printing.

⑤ A system for printing and dispensing chemical reagents in precisely controlled volumes onto a medium at a precisely controlled location. A jetting tube, comprising an orifice at one end and a fluid receiving aperture at the other end, is concentrically mounted within a cylindrical piezo-electric transducer. The fluid receiving aperture is connected to a reservoir containing a selected reagent by means of a filter. The reservoir is pressurized by a regulated air supply. An electrical signal of short duration is applied to the transducer. The pulse causes the transducer and the volume defined by the jetting tube to expand, thereby drawing in a small quantity of reagent fluid. The cessation of the pulse causes the transducer and the volume of the jetting tube to de-expand, thereby causing at least a substantially uniformly sized droplet of reagent fluid to be propelled through the orifice. The droplet may be directed to impact a printing medium or collected in a dispensing receptacle.

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## APPARATUS AND PROCESS FOR REAGENT FLUID DISPENSING AND PRINTING

BACKGROUND OF THE INVENTION

6 The present invention relates to an apparatus and process for dispensing and printing reagent fluids, wherein a transducer is used to propel small quantities of the fluid towards a positioned target.

Diagnostic assays often require systems for metering, dispensing and printing reagent fluids. In the case of metering and dispensing, such systems comprise both manual and automatic means. For purposes of practicality, the present background discussion will focus on the methods of metering and dispensing 100 micro-liter volumes or less.

10 The manual systems of metering and dispensing include the glass capillary pipet; the micro-pipet; the precision syringe; and weighing instruments. The glass capillary pipet is formed from a precision bore glass capillary tube. The pipet typically comprises a fine blown bulb and a tubular portion fine drawn to a fine point. Fluid is precisely metered by aspirating liquid through the tube into the bulb to a predetermined level indicated by an etched mark. The fluid may then be dispensed by blowing air through the tube.

15 The micro-pipet typically comprises a cylinder and a spring loaded piston. The travel of the piston is precisely determined by a threaded stop. The distance the piston travels within the cylinder and the diameter of the cylinder define a precise volume. The fluid is aspirated into and dispensed from the micro-pipet in precise quantities by movement of the piston within the cylinder.

20 The precision syringe generally comprises a precisely manufactured plunger and cylinder with accurately positioned metering marks. The fluid is introduced into and dispensed from the syringe by movement of the plunger between the marks.

Weighing techniques for dispensing fluids often simply involve weighing a quantity of fluid. The density of the fluid may then be used to determine the fluid volume.

25 Exemplary automatic metering and dispensing systems include the precision syringe pump; the peristaltic pump; and the high performance liquid chromatography (HPLC) metering valve. The precision syringe pump generally comprises a precision ground piston located within a precision bore cylinder. The piston is moved within the cylinder in precise increments by a stepping motor.

30 The peristaltic pump comprises an elastomeric tube which is sequentially pinched by a series of rollers. Often the tube is placed inside a semi-circular channel and the rollers mounted on the outer edge of a disc driven by a stepping motor. The movement of the rollers against the tubing produces peristaltic movement of the fluid.

The HPLC metering valve comprises a defined length of precision inner diameter tubing. The fluid is introduced into the define volume of the tubing with the valve in a first position and then dispensed from the tubing when the valve is placed in a second position.

35 All of the above metering and dispensing systems have the disadvantage that the volumes dispensed are relatively large. Furthermore, these systems are also relatively slow, inefficient and comprise precision fitted components which are particularly susceptible to wear.

40 The printing of reagent fluids is frequently required in the manufacture of chemical assay test strips. Selected reagents are printed in a desired configuration on strips of filter paper. The strips may then be used as a disposable diagnostic tool to determine the presence or absence of a variety of chemical components.

45 Generally, to perform a chemical assay with a test strip, the strip is exposed to a fluid or a series of fluids to be tested, such as blood, serum or urine. In some instances, the strip is rinsed and processed with additional reagents prior to being interpreted. The precise interpretation depends on the type of chemical reactions involved, but it may be as simple as visually inspecting the test strip for a particular color change.

The manufacture of test strips generally involves either a manufacturing process or a blotting process. The blotting process is the simplest manufacturing method and permits most reagents to be applied without modification. A disadvantage of this process is that it is difficult to blot the fluids onto the test strip with precision.

50 The printing process will often involve any of three well known methods: silk screening; gravure; and transfer printing. The silk screening of reagents generally involves producing a screen by photographic methods in the desired configuration for each reagent to be printed. The screen is exposed under light to a preselected pattern and then developed. The areas of the screen which are not exposed to light, when developed, become porous. However, the areas of the screen which have been exposed to light remain relatively nonporous. The screen is then secured in a frame and the test strip placed below. The desired

reagent fluid, specially prepared to have a high viscosity, is spread over the top side of the screen. The reagent passes through the porous areas of the screen and onto the test strip. The test strip is then subjected to a drying process, specific to each reagent. Once the test strip is dry, it may be printed again using a different screen, pattern and reagent.

5 The gravure method of printing reagents comprises coating a metal surface with a light sensitive polymer. The polymer is exposed to light in the desired predetermined pattern. When developed, the polymer creates hydrophilic and hydrophobic regions. The reagent is specially prepared such that when applied to the metal it will adhere only to the hydrophilic regions. After the specially prepared reagent is applied, the test strip is pressed against the metal and the reagent is transferred from the metal to the test strip.

10 The transfer printing method comprises transferring the reagents from a die to the test strip in the desired pattern. The die is made with the appropriate pattern on its surface and then coated with the desired, specially prepared reagent. A rubber stamp mechanism is pressed against the die to transfer the reagent in the desired pattern from the die to the rubber stamp. The rubber stamp is then pressed against the test strip to transfer the reagent, in the same pattern, to the test strip.

15 Each of the above-mentioned reagent printing techniques has significant disadvantages. The most common disadvantage is the requirement that the reagents must be specially prepared. Additionally, if a variety of reagents are to be printed onto a single test strip, the strip must be carefully aligned prior to each printing. This alignment procedure increases the cost and decreases the throughput of the printing process.

20 Moreover, a special die or screen must be produced for each pattern to be printed. A further disadvantage arises in that the above printing methods are unable to place reproducible minute quantities of reagent on the test strip.

It is an object of the present invention to provide a printing and dispensing method and apparatus which avoids these disadvantages.

25

#### SUMMARY OF THE PRESENT INVENTION

30 The present invention is directed to a reagent dispensing and printing apparatus and method, wherein the apparatus comprises a transducer operative to eject a substantially uniform quantity of reagent in a precise predetermined direction.

35 According to one preferred embodiment of the present invention used in dispensing reagent fluids, a jetting tube is concentrically located with a piezoelectric transducer. The jetting tube comprises an orifice at one end and a reagent receiving aperture at the other end. The receiving end of the jetting tube is connected to a filter which is in turn connected to a reservoir containing a selected reagent. A jetting control unit supplies an electrical pulse of short duration to the transducer in response to a command issued by a computer. The electrical pulse causes the volume defined by the jetting tube to expand by an amount sufficient to intake a small quantity of reagent fluid from the reservoir. At the end of the pulse duration, the transducer de-expands propelling a small quantity of the reagent fluid through the orifice and into a fluid receptacle. If desired, additional droplets may be deposited in the receptacle or the receptacle aligned with an additional jetting tube for receiving an additional reagent fluid.

40 An additional preferred embodiment of the present invention may be used for printing reagent fluids onto a print medium. In this embodiment, the jetting tube is aligned with the printing medium such that the propelled droplet impacts a precise position on the medium. The jetting tube or print medium may then be repositioned and another droplet expelled from the jetting tube. The process may be repeated until a desired configuration of the reagent fluid is printed on the medium.

45 One advantage of the present invention is that precise minute quantities of reagent fluid may be dispensed or printed in a reproducible manner. Additionally, the method and apparatus may be used to emit droplets of fluids having a wide range of reagent fluid viscosities and surface tensions. The reagents do not in general have to be specially adapted for use with the present invention.

50 The invention itself, together with further objects and attendant advantages, will best be understood by reference to the following detailed description, taken in conjunction with the accompanying drawings.

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**BRIEF DESCRIPTION OF THE DRAWINGS**

FIGURE 1 is a schematic representation of a first preferred embodiment of the present invention showing the use of multiple jetting heads to meter and dispense reagent fluid.

5 FIGURE 2a is a perspective view of a first preferred embodiment of the jetting head of the present invention.

FIGURE 2b is a cut-away perspective view of the preferred embodiment of Fig. 2a taken along lines 2b-2b with the contact pins removed.

10 FIGURE 2c is a sectional representation of the preferred embodiment of Fig. 2a taken along lines 2c-2c.

FIGURE 2d is a sectional representation of the preferred embodiment of Fig. 2c taken along lines 2d-2d.

15 FIGURE 2e is a sectional representation of the jetting tube and transducer of the preferred embodiment of Fig. 2b taken along lines 2e-2e.

FIGURE 3 is a schematic representation of a second preferred embodiment operating in the drop on demand mode as a reagent printing system.

20 FIGURE 4 is a schematic representation of a third preferred embodiment operating in the continuous mode as a reagent printing system.

FIGURE 5a is a schematic representation of a portion of the jetting head control unit showing the 25 LED strobe circuit.

FIGURE 5b is a schematic representation of a portion of the jetting head control unit showing the high voltage power supply circuit.

FIGURE 5c is a schematic representation of a portion of the jetting head control unit showing the print control circuit.

25 FIGURE 5d is a schematic representation of a portion of the jetting head control unit showing a portion of the print pulse generator.

FIGURE 5e is a schematic representation of a portion of the jetting head control unit showing an additional portion of the pulse generator.

30 FIGURE 6a is a perspective view of a second preferred embodiment of the jetting head of the present invention.

FIGURE 6b is an exploded view of the preferred embodiment of Fig. 6a.

FIGURE 7 is a sectional representation of a third preferred embodiment of the jetting head of the present invention.

35 FIGURE 8 is a sectional view of a symmetrical portion of a fourth preferred embodiment of the jetting head of the present invention.

FIGURE 9 is a graph of the drop mass of the emitted droplets as a function of emission frequency for several fluid viscosities.

FIGURE 10 is a graph of the velocity of the emitted droplets as a function of frequency for several fluid viscosities.

40 FIGURE 11 is a graph of the total weight of fluid emitted as a function of the number of emitted droplets for a given fluid.

**DETAILED DESCRIPTION OF THE PRESENTLY PREFERRED EMBODIMENTS**

45 Turning now to the drawings, Fig. 1 shows a schematic representation of a first preferred embodiment of a reagent dispensing system generally represented as reference numeral 30. The dispensing system 30 comprises a plurality of reagent fluid reservoirs 200, a plurality of filters 300, a plurality of reagent jetting heads 400, a plurality of jetting head control units 500, an interface unit 600, a computer 700, transportation unit 902, a plurality of fluid mixing cells 904 and a detection station 906.

50 The reservoir 200 holds a selected quantity of reagent fluid for dispensing. The reservoir 200 is maintained at atmospheric pressure by suitable means such as an atmospheric vent. The reagent fluid is transferred from the reservoir 200 through the filter 300 to the reagent jetting head 400. The filter 300 is placed between the reservoir 200 and the jetting head 400 to ensure that any particular foreign matter in the reagent fluid is trapped before entering the jetting head 400.

55 The plurality of jetting heads 400 and the detection station 906 define a processing path. Each jetting head 400, which is described in detail below, ejects uniformly sized droplets 2 of reagent fluid. The droplets 2 are propelled, with controlled velocity and direction, towards a selecting mixing cell 904 positioned along

the processing path by the transportation unit 902. The mixing cells 904 are comprised of non-reactive material and function as minute holding tanks for the dispensed reagent fluid.

5 The plurality of jetting heads 400, shown in Fig. 1, are positioned sequentially along the processing path. Alternately, some or all of the plurality of jetting heads 400 may be positioned with respect to the transportation unit 902 such that the heads 400 direct the droplets 2 into a selected mixing cell 902 simultaneously.

10 The jetting heads 400 and the transportation unit 902 are controlled by the computer 700. The computer 700 issues commands to an interface unit 600 which is electrically connected to the transportation unit 902 and to the jetting head control unit 500. The interface unit 600 is of conventional design and is used to control the transfer of information between the computer 700 and the jetting control unit 500. The interface unit 600 is also used to control the transfer of information between the computer 700 and the transportation unit 902.

15 A first embodiment of the reagent jetting head is shown in Figs. 2a - 2e and generally represented by numeral 400. The jetting head 400 comprises a two piece symmetrical housing 402, 404. The housing 402, 404, when assembled, is adapted to form an orifice aperture 406, an air vent and reagent supply channel 410 and a transducer chamber 403, shown in Fig. 4b. Four screws 408, adapted to respective housing screw apertures 416, hold the housing 402, 404 in an assembled configuration.

20 The jetting head 400 further comprises a jetting tube 432, a piezo-electric transducer 434 and a reagent fluid supply tube 430. The jetting tube 432 defines a tapered orifice 433 at one end and a fluid receiving aperture 431 at the other end for expelling and receiving fluid, respectively. The piezo-electric transducer 434 is cylindrically shaped and secured concentrically about the mid-region of the jetting tube 432 with epoxy or other suitable means.

25 The piezo-electric transducer 434, shown in Fig. 2e, defines a first and second end and comprises a section of cylindrically shaped piezo-electric material 435. An inner nickel electrode 437 covers the inner surface of the cylinder 435. The electrode 437 wraps around the first end of the cylinder 435 a sufficient distance to enable electrical connection external to the cylinder 435.

30 A second nickel electrode 436 covers the majority of the outer surface of the cylinder 435. The second electrode is electrically isolated from the first electrode 437 by an air gap at the face of the second end of the cylinder 435 and by an air gap on the outer surface of the cylinder 435 near the first end. When an electrical pulse is applied to the first and second electrodes 437, 436 a voltage potential is developed radially across the transducer material 435. The voltage potential causes the radial dimensions of the transducer 435 to change, which causes the volume defined by the transducer 434 to also change.

35 The jetting tube 432 is positioned in the transducer chamber 403 such that the receiving end 431 extends beyond the rearward end of the transducer 434. The receiving end 431 of the jetting tube 432 is inserted into one end of a reagent supply tube 430. The supply tube 430 is sealingly held to the jetting tube 432 by concentric teeth 412 formed by the housing sections 402, 404. The teeth 412 not only seal the supply tube 430 to the jetting tube 432, but, also, seal the supply tube 430 to the housing 402, 404.

40 The second end of the supply type 430 passes through the channel 410 and into a reagent reservoir 200. The reservoir 200 contains the reagent fluid to be dispensed by the jetting head 400. As the reagent fluid is dispensed, air is supplied to the reservoir 200 through the channel 410 to prevent the creation of a vacuum in the reservoir 200. The reservoir 200 is releasably attached to the housing 402, 404 and held in place by frictional forces. A reservoir cap 202 is flexibly attached to the reservoir 200 and adapted such that the cap 202 may be used to secure the opening in the reservoir 200 when the reservoir 200 is disengaged from the housing 402, 404.

45 The position of the jetting tube 432 defines the horizontal plane of the jetting head 400. The jetting tube 432 and the transducer 434 are held in a pre-defined vertical relationship with respect to the housing 402, 404 by means of two upper vertical alignment pins 418 and two lower vertical alignment pins 418. The two upper vertical alignment pins 418 extend horizontally from the housing section 402 into the transducer chamber 403. Similarly, the two lower vertical alignment pins 418 extend horizontally from the housing section 404 into the transducer chamber 403. Each vertical alignment pin 418 is formed integrally with the respective housing sections 402, 404.

50 The jetting tube 432 and the transducer 434 are held in a predefined horizontal relationship with respect to the housing 402, 404 by means of four horizontal alignment pins 424. Two of the horizontal alignment pins 424 extend horizontally from the housing section 402 approximately midway into the transducer chamber 403. Similarly, two of the horizontal alignment pins 424 extend horizontally from the housing section 404 approximately midway into the transducing chamber 403. Each horizontal alignment pin 424 is formed integrally with the respective housing section 402, 404. The alignment pins 418, 424, sealing teeth 412 and orifice aperture 406 are aligned and adapted to hold the jetting tube 432 and transducer 434 such

that the orifice 433 of the jetting tube 432 extends into the orifice aperture 431.

5 An electrical transducer activation pulse is supplied to the piezo-electric transducer 434 from the jetting head control unit 500 by means of two contact pins 422. A quantity of fluid will be dispensed from the jetting tube for each applied activation pulse. The activation pulse can be produced by a variety of conventional circuits or commercially available units. Therefore a detailed description of such a circuit will not be provided. However, a circuit for producing a series of activation pulses is provided in the description of the printing embodiment below. Due to the differing constraints involved in dispensing and printing, the circuit in the printing embodiment is not required to produce only a single pulse. However, one skilled in the art could, if desired, modify the circuit to produce a single pulse on demand for use in the dispensing embodiment.

10 Each contact pin 422 defines an enlarged head 423 which is adapted to contact the respective first and second electrodes 437, 436 located on the outer surface of the transducer 434. Two contact pin holders 414, integral with the housing 402, 404, are positioned to hold the respective contact pins 422 under the pin heads 423 such that each pin head 423 electrically engages the appropriate electrode 437, 436 of the transducer 434. Two contact pin engaging posts 420 extend from the housing 402, 404 opposite the contact pin holders 414 to engage and hold the contact pins 422 against the contact pin holders 414. The ends of the contact pins 422 opposite the pin heads 423 extend through the housing 402, 404 by means of contact pin apertures 421. Since the housing sections 402, 404 are formed symmetrically to one another, the contact pins 422 may be optionally attached above the transducer 434.

15 20 In operation, the reservoir 200 containing reagent fluid is fastened to the jetting head 400 such that the fluid supply tube 430 extends into the reagent fluid. The filter 300 may be fitted to the free end of the supply tube 430 or positioned inside the reservoir 200. Air is supplied through the channel 410 around the supply tube 430 to prevent the reservoir 200 from falling below atmospheric pressure. The air is prevented from entering around the supply tube 430 and into the transducer chamber 403 by the seal created 25 between the sealing teeth 412 and the supply tube 430. The jetting tube 432 may be primed by slightly pressurizing the reservoir 200 to cause the reagent fluid to travel through the supply tube 430 and into the jetting tube 432. Once primed, the fluid is prevented from substantially withdrawing from the jetting tube 432 by the surface tension of the reagent fluid at the orifice 433.

25 30 The transducer activation pulse is conducted to the contact pins 422 of the jetting head 400. The contact pins 422 communicate the high voltage pulse to the electrodes 437, 436 of the transducer 434 with polarity such that the concentrically mounted transducer 434 expands. The rate of expansion is controlled by the rise time of the high voltage pulse which is preset to generate a rapid expansion. The expansion of the transducer 434 causes the jetting tube 432, which is epoxied to the transducer 434, to also expand. The expansion of the tube 432 generates an acoustic expansion wave interior to the tube 432 which travels 35 axially towards the orifice 433 and towards the fluid receiving aperture 431. When the expansion wave reaches the orifice 433, the reagent fluid is partially drawn inwardly. However, the surface tension of the fluid acts to inhibit substantial inward fluid movement.

35 40 When the expansion wave reaches the end 431 of the tube 432, the expansion wave is reflected and becomes a compression wave which travels towards the center of the piezo-electric tube 434. The high voltage pulse width is adapted such that when the reflected compression wave is beneath the piezo-electric tube 434, the high voltage pulse falls, resulting in a de-expansion of the transducer 434 and the jetting tube 432. This action adds to the existing acoustic compression wave in the interior of the jetting tube 432. The enhanced compression wave travels toward the orifice causing reagent fluid to be dispensed from the tube 432. The fluid is propelled from the orifice 433 as a small droplet 2 and deposited in the selected mixing cell 904 positioned by the transportation unit 902. One droplet 2 is dispensed for each transducer activation pulse. This mode of dispensing is referred to as the drop on demand mode.

45 50 In some instances, the droplet 2 may be accompanied by at least one smaller satellite droplet. However, even if satellite droplets are present, the volume and velocity of the reagent droplets 2 are highly reproducible. This reproducibility allows for precise dispensing of uniform, controllably sized droplets 2 of reagent fluid into the mixing cell 904.

The droplets 2 of reagents impact the mixing cell 904 with sufficient force and volume to cause fluidic mixing of the reagents. Once the desired amounts of the selected reagents are deposited in the selected mixing cell 904, mixing cell 904 is transported to the detection station 906 where the mixed reagents may be extracted for use or analyzed for assay results.

55 60 The dispensing system 30 provides numerous advantages based upon the ability of the reagent jetting head 400 to rapidly and reproducibly eject uniform quantities of a wide range of reagents. The reaction times of some chemical processes are dependent upon the volume of the reagents used. The ability of the dispensing system 30 to dispense such minute amounts of reagents thereby reduces the processing time

of certain chemical assays. Furthermore, some chemical assays require a wide range of dilution ratios. Many conventional dispensing systems are unable to dispense the reagents in volume small enough to make the desired assay practical. The dispensing system of the present invention overcomes this disadvantage.

5 In addition to dispensing reagent fluids, certain embodiments may be used for precision printing of reagents onto a printing medium such as filter paper to produce an assay test strip. A printing system 10 using the present invention is represented in Fig. 3. Structure similar in form and function to structure described above will be designated by like reference numerals. The printing system 10 comprises a reagent fluid reservoir 200, a filter 300, a reagent jetting head 400, a jetting head control unit 500, an interface 600, a computer 700, and an x-y plotter 800.

10 The x-y plotter 800 is a commercially available pen plotter, mechanically modified in a conventional manner such that the pen is replaced with the jetting head 400. The general operation and structure of the plotter 800 will not be described in detail. The plotter 800 accepts commands from the computer 700 thru a standard RS-232 serial interface contained within the interface unit 600. The plotter 800 processes the 15 commands and produces control signals to drive an x-axis motor (not shown) and a y-axis motor (not shown). The x-axis motor is used to position the jetting head 400 and the y-axis motor is used to position a drum (not shown) to which the printing target 1 is attached.

The plotter 800 produces a pen down signal PENDN. This signal is applied to the control unit 500 and indicates that the plotter 800 is ready to begin a printing operation.

20 The control unit 500 also receives control signals from the interface unit 600. These signals include signals HIGHER', LOWER' to control the magnitude of the pulse applied to the transducer 434; a reset signal RST to reset the control unit 500; and a series of print signals PRT'. The generation of these signals will not be described in detail since their production is performed by the conventional interface unit 600.

25 The jetting head 400 and fluid supply system 200, 300 are initialized and operate substantially as described above. The jetting head control unit 500, shown in Figs. 5a - 5e comprises a print control circuit 510, a pulse generator 530, a high voltage supply 540, and a strobe pulse generator 560. The control unit 500 also comprises a power supply. However, since the power supply is of conventional design it will not be shown or described in detail.

30 The print control circuit 510 receives the pen down signal PENDN from the plotter 800 and comprises a transistor Q100, a one-shot circuit U100, two NAND-gates U101, U102, a line decoder multiplexer U107 and four inverters U103-U106. The pen down signal PENDN is applied to the base of the transistor Q100 by resistors R100, R101 and diode D100. The emitter of transistor Q100 is tied to ground and the collector is connected to the +5 volt supply by resistor R102.

35 The one-shot U100 comprises inputs A, B and an output Q. The B input of the one-shot U100 is connected to the collector of the transistor Q100 and the A input is tied to ground. The time period of the pulse produced by the one-shot U100 is determined by a resistor R104, a variable resistor R105 and a capacitor C100. The output Q of the one-shot U100 is combined with the collector output of the transistor Q100 by the NAND-gate U101 and then inverted by the NAND-gate U102. The circuit is operative to produce an adjustable delay in the application of the pen down signal PENDN to the control unit 500.

40 The line decoder U107 is circuited to function as a 3 input AND-gate. The output of the NAND-gate U102 is applied to the first input of the decoder U107; the print signal line PRT' comprising a series of pulses from the interface unit 600 is applied to the second input; and a jetting head ON/OFF signal from switch S1 is applied to the third input. The inverter U106 inverts the output of the line decoder U107 to generate the print control signal PRT' and the inverters U103-U105 invert the control signals LOWER', 45 HIGHER', and RST signals, respectively.

45 The high voltage supply 540, shown in Fig. 5b, provides +175 volts DC to produce a maximum pulse of +150 volts peak to peak at the reagent jetting head 400. The high voltage supply 540 comprises differential amplifier U12 and transistors Q1, Q2, Q13, Q14. A stable reference voltage of -2.5 volts DC is produced at the junction of a reservoir R13, connected to the -15 volt supply, and a diode CR6, connected to ground. The reference voltage is combined with a resistor R14 to produce an adjustable, stable voltage reference for the amplifier U12. The reference voltage is applied to the inverting input of the amplifier U12 through a resistor R11. The noninverting input of the amplifier U12 is connected to ground by a resistor R12. The amplifier U12, in combination with a feedback resistor R10, produces an output signal proportional to the difference of the voltage reference signal and the ground potential.

55 The output of the amplifier U12 is applied to the base of the transistor Q2 whose collector is connected to the +15 volt supply. The signal produced at the emitter of the transistor Q2 is applied to the base of the transistor Q1 through resistors R8, R6, R5, a transformer L1 and diodes CR4, CR2, CR1. The emitter of the transistor Q1 is connected to ground and the collector is connected to the +15 voltage supply through the

transformer L1. A diode CR3 connects the collector of the transistor Q1 to the junction of the resistor R5 and the diode CR4. The transistor Q1 is biased for proper operation by resistors R7, R6, R5. The resistor R7 and a capacitor C22 connect the junction of the resistor R8, R6 to the +15 voltage supply.

5 The transistor Q1 and the transformer L1 form a "flyback" blocking oscillator. Any increase in current supplied by the transistor Q1 produces an increase in energy transferred through the secondary winding of the transformer L1 and diode CR5. Therefore, an increase in current supplied by the transistor Q1 results in an increase in power available to the high voltage output. The diodes CR1-CR4 form a "Baker clamp" which prevents transistor Q1 from saturating. The clamp thereby avoids transistor storage time.

10 The diode CR5 is connected to a multiple pi filter formed by the inductors L3, L2, capacitors C24, C21, C41 and resistors R29. The multiple pi filter attenuates ripple and switching spikes in the signal supplied to the transistor Q13 which produces the high voltage output V+++. A resistor R64 connects the base of the transistor Q13 to the emitter and to the resistor U29. The base is also connected to the collector of the transistor Q14 by a resistor R65. The base of the transistor Q14 is connected to the +15 volt supply by a resistor R67 and to ground by a resistor R66. The emitter of the transistor Q13 provides a signal HV 15 SENSE which is fed back to the inverting input of the amplifier U12 through a resistor R9. The high voltage output V++ is produced at the collector of the transistor Q13. The proper biasing of the transistor Q13 is provided by resistor R64 and the biasing circuit comprising the transistor Q14, resistors R67, R66, R65.

15 The pulse generator 530, shown in Figs. 5d, 5e, comprises an opto-isolator U18, a one-shot U23, a digital to analog (D/A) converter U30 and two binary counters U24, U25. The pulse generator 530 accepts control signals PRT, LOWER, HIGHER, RST and produces the activation pulse which is applied to the transducer 434. In normal operation, the PRT control signal is supplied to the opto-isolator U18 by a jumper JMP between contact points E5, E6. The opto-isolator U18 is of conventional design and comprises a light emitting diode (LED) circuit and a photo-element circuit. A resistor R15 operates as the load resistor for the LED circuit of the isolator and a capacitor C25 suppresses transient noise on the voltage supply to the isolator U18. The output of the isolator U18 is applied to one input of the one-shot U23 whose time constant is adjustably determined by resistors R38, R25 and a capacitor C30. The pulse from the non-inverting output of the one-shot U23 is fed to the base of a transistor Q9. A resistor R39 sets the approximate base current of the transistor Q9 which is used as a level shifter for converting the CMOS signal level to the +15 volt DC signal level.

20 30 The control of the rise and fall rates of the pulse generator 530 is accomplished by directing a pair of current source transistors Q11, Q12 to charge and discharge a capacitor C57. The transistor Q11 is operative as a source of current and the transistor Q12 is operative as a sink for current. A transistor Q10 controls the level of the current by applying an appropriate bias current through a resistor R56 to the base of the transistor Q11. The biasing of the transistors Q11, Q12 is critical to the proper rise and fall rates. 35 Therefore precision voltage references CR13, CR15 are used to provide respective bias reference voltages. A temperature compensation network is formed from zener diodes CR14, CR16 and resistors R55, R54 to maintain stable operation of the transistors Q11, Q12, respectively. The variable resistors R49, R52 may be used to adjust the fall time and rise time, respectively, of the output pulse applied to the reagent jetting head 400. A plurality of resistors R45, R46, R47, R48, R49, R51, R52, R53, R56, R57, R58 are used to 40 properly bias the transistor Q10, Q11, Q12 and capacitors C55, C60 are circuited to maintain stability of the circuit.

45 The impedance of the output stage of the rise and fall circuitry Q10, Q11, Q12 is very high. With such a high impedance, circuit elements attached to the capacitor C57 could affect the linearity of the rise and fall time constants. Therefore, an FET input operational amplifier U32 is used as an impedance interface. The amplifier U32 is configured in the noninverting mode and circuited with capacitors C58, C59 for stability.

50 The output of the amplifier U32 is applied to an inverting amplifier U31 by means of a resistor R62. The amplifier U31 inverts and conditions the pulse control signal with the aid of resistors R59, R60. Resistors R61, R63, connected to the -15 voltage supply, provide a means for adjusting the DC level offset of the amplifier U31 output signal. Capacitors C51, C52 are connected to enhance the performance and stability of the circuit.

55 The output of the amplifier U31 is applied by means of a resistor R41 to the positive voltage reference signal input REF(+) of the D/A converter U30. The negative voltage reference signal input REF(-) is tied to ground by a resistor R40. The D/A converter U30 produces output signals IOUT, IOUT' which are proportional to the difference between the positive and negative voltage reference signal inputs REF(+), REF(-). Capacitors C48, C49, C50 are connected to the D/A converter U30 to enhance stability.

60 The D/A converter outputs IOUT, IOUT' are also proportional to an 8-bit binary value applied to inputs B1-B8. The binary value is supplied by the counters U24, U25 which are controlled by the function signals LOWER, HIGHER and RST. The LOWER signal and the HIGHER signals are applied to the count up and

count down inputs CU, CD of the counter U24 by means of opto-isolators U19, U20. The carry and borrow outputs CY, BR of the counter U24 are connected with the count up and count down inputs CU, CD of the counter U25. The reset inputs RST of both counters U24, U25 receive the RST signal by means of an opto-isolator U21. Resistors R16, R17, R18 are used as load resistors for the LED circuits of the isolators U19, U20, U21 and capacitors C26, C27, C28 are used to enhance the stability of the isolator circuits.

5 The counters U24, U25 may optionally be preloaded to the selected 8-bit binary value through input lines TP0-TP7. The input lines TP0-TP7 are normally biased to the logical high signal state by resistive network U22. The selected binary value is loaded into the counters U24, U25 by pulling the respective inputs TP0-TP7 low and applying an external, active low, load signal EXT LOAD to pin TP8. The load signal 10 pin TP8 is connected to the load inputs LOAD of the counters U24, U25 and conditioned by a clipping circuit comprised of diodes CR9, CR10 and a pull-up resistor of the resistor network U22.

15 The noninverted and the inverted outputs IOUT, IOUT<sup>+</sup> are connected to the inverting and noninverting inputs of a differential amplifier U29. The output of the amplifier U29 is fed back to the inverting input by a resistor R50. The amplifier U29 converts the current output of the D/A converter U30 to a voltage output.

15 Capacitors C56, C47 are provided to enhance circuit stability.

20 The output of the amplifier U29 is applied to the noninverting input of the amplifier U28. The output of the amplifier U28 is fed back to the inverting input by means of a capacitor C46 and a resistor R37. The inverting input is also connected to ground by a resistor R36. To enhance the frequency response of the amplifier U28, a resistor R43 and a capacitor C54 are connected between the frequency compensation input 25 FC and ground. An adjustable DC offset is provided by connecting the output offset inputs OF, OF with a variable resistor R42. The wiper of the resistor R42 is connected to the high voltage power supply output V++.

25 The output of the amplifier U28 is also connected to the base of a transistor Q4 and through diodes CR11, CR12 to the base of a transistor Q7. The transistor Q4, Q7, Q3 and resistors R30-R35 form an output circuit capable of driving high capacitive loads at high slew rates and wide bandwidth. The variable resistor R31 may be used to set the maximum current through the bias network R30, R33 by measuring the voltage drop across resistor R35.

30 The strobe generator 560 produces a strobe pulse and comprises transistors Q101-Q105 and a one-shot circuit U108. The strobe intensity is determined by the circuit comprising the transistors Q101-Q104 and resistors R109-R115. The circuit is connected to the anode of the LED 900 and receives two inputs from the interface unit 600 to produce four levels of light-intensity in the LED 900.

35 The activation band duration of activation of the LED 900 is determined by the one-shot U108 and the transistor Q105. The one-shot U108 comprises inputs A, B and an output Q. The strobe signal STROBE is applied to the B input from the interface unit 600. The duration of the one-shot U108 output pulse is controlled by the adjustable RC network R107, R108. The output Q is applied to the base of the transistor Q105 by resistor R108. The collector of the transistor Q105 is connected to the cathode of the LED 900 to draw current through the LED 900.

40 The computer 700, control unit 500 and plotter 800 must be initialized. The initialization of the computer 700 and the plotter 800 will not be discussed since these units are of conventional design and operation.

45 To initialize the jetting head control unit 500, the computer 700 directs the interface unit 600 to issue a reset command. The reset signal RST is conducted to the control unit 500 whereupon the counters U24, U25 are cleared. The computer 700 then retrieves from its memory, or by conventional operator input, the desired digital setting for the D/A converter. This setting may also be calculated from data and may be tailored to specific sizes of jetting heads 400 or reagent fluids. The computer 700 then issues a series of commands, through the interface unit 600, to increment or decrement the counters U24, U25 to correspond to the desired binary setting. If the command directs that the counters are to be raised, then the HIGHER signal is applied through the opto-isolator U20 to the count up CU input of the counter U24. Similarly, if the command directs that the counters are to be lowered then the LOWER signal is applied through the opto-isolator U19 to the count down CD input of the counter U24. Since the carry and borrow outputs CY, BR of the counter U24 are connected to the count up and count down inputs CU, CD, respectively, of the counter U25, the digital setting applied to the D/A converter U30 may range from 0 to 255. Alternately, the counters U24, U25 could be initialized to a desired setting by loading the binary value on the lines TP0-TP7 and strobing the EXT LOAD line.

50 Once the control unit 500 and the plotter 800 are initialized, the printing cycle may begin. The computer 700 issues a command to the interface unit 600 to produce the series of PRT signal pulses. The computer 700 then commands the plotter 800 to print, for example, a line along a selected path. The plotter 800 positions the jetting head 400 and target 1 and issues the pen down signal PENDN. The signal is delayed by the print control circuit 510 to ensure that the target 1 is properly positioned. At the expiration of the

delay, the signal is ANDed with the closed-enable switch S1 and the series of print pulses PRT. The result of the AND operation is the application of the PRT pulses to the pulse generator circuit 530.

The PRT signal is applied through the jumper JMP to the opto-isolator U18 and then to the one-shot U23. The one-shot U23 produces a pulse signal which is then converted from CMOS signal levels to the 15 volt DC signal level by the transistor Q8. The rise and fall circuitry comprising Q10, Q11, Q12 converts the square wave pulse into a pulse having the rise and fall characteristics preset by the resistors R49, R52. The conditioned pulse is then amplified by the amplifier U32 and applied to the amplifier U31.

The amplifier U31 converts the polarity of the conditioned pulse to that acceptable by the D/A converter U30 and supplies an adjustable DC offset. The DC offset is used to counteract possible distortion attributable to the amplifier U31. The distortion arises in that, for the amplifier U31 to be adequately responsive, a small degree of current must flow through the resistor R41. This current creates an offset condition at the output of the amplifier U29 which is then scaled by the D/A converter U30 in correspondence with the binary data. The resistor R63 allows a small amount of current to be applied to the amplifier U31 to control the offset voltage attributable to the current flowing through the resistor R41.

15 The D/A converter U30 scales the difference between the inputs REF(+), REF(-) using the binary data supplied to input lines B1-B8 to produce a current output pulse IOUT and a current inverted output pulse IOUT'. The two outputs IOUT, IOUT' are fed to the amplifier U29 which convert the current outputs into a single voltage output. The scaled, conditioned pulse is then applied to the output circuit comprising the amplifier U28 and the transistors Q3, Q4, Q5, Q6, Q7. The circuit produces a high voltage pulse with the aforementioned rise and fall characteristics to drive the piezo-electric transducer 434.

20 The high voltage pulse is applied to the transducer 434 and causes a droplet 2 of fluid to be propelled onto the target 1. Since the pen down signal PENDN is still applied, additional droplets 2 are produced from the jetting head 400. The plotter 800 moves the jetting head 400 and target 1 along the desired path during the emission of the droplets 2 to produce the desired printed line. When the printing is complete, the plotter 25 800 removes the pen down signal PENDN and the droplet emission stops. Of course it should be understood that dots, circles and the like could be produced by appropriate positioning of the target 1 and jetting head 400.

25 The size and uniformity of the droplets 2, as well as the presence of any satellite droplets, may be observed with the aid of the scope 950 and the LED 900. The scope 950 and the LED 900 are positioned such that the droplets 2 pass between the scope 950 and the LED 900 and within the focal range of the scope 950. The strobe pulse when applied to the LED 900 causes the LED 900 to momentarily flash. The timing of the activation and the width of the pulse may be adjusted such that the flash occurs when the fluid, expelled in response to the high voltage pulse, is between the scope 950 and the LED 900. The dispensed quantity of fluid may then be observed in flight or at or near the moment of separation from the orifice 433. Corrections based on the observation may then be made to the system 10.

30 Since each droplet 2 is small in volume, the droplet 2 may be rapidly absorbed by the target 1, thereby allowing rapid and precise placement of a variety of reagents on the target 1 with reduced drying time and reduced potential of fluidity mixing. In addition, the ability to place small droplets 2 in a precise manner enables the target 1 to be printed in a high density matrix with a variety of reagents as isolated matrix elements.

35 In some printing applications, particularly when printing fluids of low viscosity and surface tension, it may be desirable to force the fluid through the jetting tube 432 under pressure and allow the vibrations produced by the transducer 434 to break the emitted fluid stream into precise droplets 2. Under this mode of printing, the emission of droplets 2 can not be stopped by cessation of the transducers activation pulse. It is therefore necessary to prevent fluid emission by other means. One preferred means of momentarily stopping emission of the droplets is shown schematically in Fig. 4. In this arrangement, structure similar to structure represented in Fig. 3 in form and function, is represented by like reference numerals.

40 The arrangement, generally represented by the numeral 20, includes a closed reagent recirculation system comprising a normally close three way valve 970, a sump 960 and a recirculation pump 980. In the continuous mode, the reagent fluid is forced out the orifice 433 by hydraulic pressure and broken into a series of substantially uniform droplets 2 by movement of the transducer 434. A regulated, filtered air supply 100 is used to pressurize the reagent fluid reservoir 200. The reagent fluid within the reservoir 200 may optionally be agitated by a magnetic stirrer unit 990. This is especially useful for reagent fluids comprising suspended particles.

45 The three-way valve 970 comprises a common channel, a normally open channel and a normally closed channel. The fluid is forced through the filter 300 and applied to the normally closed channel of the valve 970. When the normally closed channel is closed, the normally open channel of the valve 970 functions as a vent for the reagent jetting head 400. The common channel is connected to the reagent supply tube 430

of the jetting head 400. The reagent supply tube 430' is also connected to the sump 960.

In operation, the normally closed channel is opened by an appropriate signal supplied by the computer 700 which also closes the normally open channel. When the normally closed channel is opened, fluid is permitted to pass to the sump 960 and to the jetting head 400. The sump 960 collects the reagent fluid not transferred to the jetting head 400. The sump 960 supplies the collected fluid to the inlet side of the recirculating pump 980 which returns the fluid to the reservoir 200. The returned fluid is then mixed with the contents of the reservoir 200 and is available for recirculation.

When operating in the continuous mode, rather than interrupt the continuous stream of print pulses to the jetting head 400, the printing may be momentarily stopped by closing the normally closed channel of the valve 970. The closing of the normally closed channel stops the flow of reagent fluid to the jetting head 400 and allows the jetting head 400 to vent to atmospheric pressure. With the fluid supply blocked, the transducer 434 is unable to expel further droplets 2. Thus, if positioning of the target 1 by the plotter 800 requires a longer time interval than the time between droplet 2 emission, the computer 700 may close the normally closed channel of the valve 970. The plotter 800 may then position the target 1 or position a new target 1 as desired.

When printing, the active ingredient of the reagent is tailored to achieve a desired concentration per unit area on the target 1. However, to a certain extent the final concentration per unit area can be adjusted by varying the density of the droplets 2 printed on the target 1. The preferred embodiment is particularly well suited to this application due to its ability to print precise, discrete dots of reagent.

A second preferred embodiment of the jetting head is illustrated in Figs. 6a-6b and is generally represented as 400'. The jetting head 400' comprises housing formed into three sections 401', 402', 403'. The housing section 403' comprises a recessed region which forms the reagent fluid reservoir 200' when the housing section 403' is positioned against housing section 402'.

The jetting head 400' further comprises a piezo-electric transducer 434' and a reagent jetting tube 432' similar to those of the first embodiment. The jetting head 400' and the transducer 434' are most clearly shown in Fig. 6b. The jetting tube 432' defines an orifice 433' at one end and a reagent fluid receiving aperture 431' at the other end. The transducer 434' is mounted to the jetting tube 432' concentrically about the mid-region of the tube 432' with epoxy.

The transducer 434' and the jetting tube 432' are positioned in channels 420', 418', 416' located in the housing sections 402', 401'. The channel 416' comprises a plurality of sealing teeth 412' operative to engage and seal against the fluid receiving end 431' of the jetting tube 432'. The channel 416' is connected to the reagent fluid supply channel 430'. The supply channel 430' is connected with the fluid reservoir 200' by means of an aperture 431' through the housing section 402', shown in Fig. 6b.

The reservoir 200' comprises a flexible reservoir lining 201' adapted to contain the reagent fluid. The lining 201' comprises one aperture which is connected to the housing 402' to allow the fluid to pass from the lining 201'. A vent (not shown), located in the housing 403', allows the space between the reservoir 200' and the lining 201' to be vented or pressurized. A filter 300' is positioned within the aperture 202' to trap unwanted particulate foreign matter.

Electrical pulses are supplied to the transducer 434' by means of two contact pins 422'. The pins 422' are inserted through respective apertures 419' of the housing section 402' and respective apertures 421' of the housing section 403'. Two thin electrically conductive strips 410', 411', shown in Fig. 6b, are used to connect the transducer 434' with the contact pins 422'. A protective shield 405' extends from the housing position 403' to partially isolate the protruding portions of the contact pins 422'.

The function and operation of the jetting head 400' is similar to that of the jetting head 400 and therefore will not be discussed in detail. The collapsible inner lining 201' of the reservoir 200 allows the jetting tube 432' to be primed by pressurizing the reservoir 200' through the vent 205'. Once primed, the jetting head 400' may be used as described above in reference to the jetting head 400.

The jetting head 400' provides an advantage in that the entire fluidic system is contained in one housing. Such containment allows for fast and efficient replacement of the jetting heads without fluid contamination problems.

A third preferred embodiment of the jetting head is shown in Fig. 7 and generally represented as 400''. The jetting head 400'' comprises a housing 403'', a reagent fluid supply tube 406'', a piezo-electric transducer 434'' and an orifice plate 404''. The housing 403'' defines a conically shaped fluid chamber 432''. An orifice plate 404'', defining an orifice 433'', is fastened to the housing 403'' such that the orifice 433'' is located at or near the apex of the conical fluid chamber 432''.

The fluid feed tube 406'' is attached to the housing 403'' and defines a supply channel 430''. The supply channel 430'' is in fluid communication with the fluid chamber 432'' by means of a connecting channel 431''. The base of the fluid chamber 432'' is formed by the disc-shaped transducer 434''. The transducer 434'' is

held in position by a hold down plate 402" attached to the housing 403". The electrical connections to the transducer 434" are of conventional design and are therefore not shown. The housing 403" further comprises a threaded aperture 406" for mounting the jetting head 400".

6 The jetting head 400" operates in a manner similar to the jetting heads described above. However, in this jetting head the transducer 434" is normally disk shaped. When the electrical pulse is applied, the transducer 434" bends slightly, thereby altering the volume of the conically shaped jetting chamber 432". The change in volume of the chamber 432" causes the expulsion of fluid through the orifice 433" and the intake of fluid through the supply channel 430" as described in reference to the jetting head 400.

10 A fourth preferred embodiment of the jetting head is shown in Fig. 8 and is generally represented as 400". The jetting head 400" is very similar in form and function to the jetting head 400 and will not be described in detail. The jetting head 400" comprises two symmetrical housing sections. The sections may be connected together by means of apertures 409" and screws, not shown. When assembled, the housing sections 404", 402" form a T-shaped supply channel 410".

15 In operation, the jetting head 400" functions in a manner similar to the jetting head 400. The jetting head 400" is especially suited for use in the continuous mode, but may also be used in the drop on demand mode. In the continuous mode, the fluid is circulated continuously through the supply channel 430" allowing the jetting tube 432" to withdraw as much fluid as required.

20 By way of illustrating and with no limitations intended the following information is given to further illustrate the above described embodiments. The computer 700 is an IBM Corporation Personal Computer with 640 kbytes of RAM memory. The interface unit 600 is a Burr Brown interface unit model number PC 20001. The plotter 800 is manufactured by Houston Instrument as model number DMP-40. Communication between the plotter 800 and the interface unit 600 is performed through a standard asynchronous serial communication port.

25 The electrical pulse applied to the jetting head 400 to activate the transducer 434 comprises a rise time of approximately 5 usecs, a fall time of approximately 5 usecs and a pulse width of approximately 35 usecs. When the transducer 434 is operated in the drop on demand mode, the voltage potential of the pulse is 60 volts plus or minus 10 volts and the pulse frequency can be up to 4 khz. When the transducer 434 is operated in the continuous mode, the voltage potential of the pulse is 30 volts plus or minus 10 volts and the pulse frequency can be up to 10 khz.

30 The jetting tube 432 is manufactured from a pyrex glass tube and measures .027 inches outside diameter and .020 inches inside diameter. The tube is drawn to a closed taper in an electric furnace. The tapered end is then cut and ground to a desired orifice opening of .002 to .004 inches in diameter. The tube is cut to a final length of .945 inches in the case of the dispenser embodiment and ultrasonically cleaned in acetone. After being cleaned and dried the large end of the tube is fire polished. If desired, the orifice end of the tube may receive a coating, such as a hydrophobic polymer, to enhance droplet separation from the tube.

35 The supply tube 430 is formed from .023 inch inside diameter and .38 inch outside diameter polyethylene tubing produced by Intramedic Corp. as model number #14 170 11B. During assembly, one end of the tubing is stretched over a warm tapered mandrel. The stretched end of the supply tube 430 is then inserted over the large fire polished end of the jetting tube 432. The assembly is then cleaned and baked in a circulating air oven at 50°C. for 10 minutes.

40 The transducer 434 was purchased from Vernitron of Cleveland, Ohio as model number PZT-5H. The electrodes 437, 436 are comprised of nickel and are separated from each other on the outer surface of the transducer by approximately .030 inches. The jetting tube 432 is inserted into the cylindrical piezo-electric tube 434 and secured with epoxy manufactured by Epoxy Technology of Bellanca, Massachusetts as model number 301. The epoxy is applied at the junction of the tube 432 and transducer 434 with a syringe. The epoxy flows along the tube 432 inside the transducer 434 by capillary action. The assembly is then baked in a circulating air oven at 65°C. for one hour to cure the epoxy.

45 The contact pins 422 are secured to one of the housing sections 402, 404 with a drop of epoxy. The transducer jetting tube 434, 432 is placed in the housing such that the orifice end 433 of the tube 432 protrudes approximately .030 inches from the housing 403, 404. A drop of silver epoxy is placed between each contact pin 422 and the transducer 434 to ensure a secure electrical connection. Epoxy is also applied to the junction of the housing 402, 404 and supply tube 430. The other section of the housing 402, 404 is then screwed into place.

50 The periphery of the housing 402, 404 is sealed with a capillary sealer such as cyclohexanone. Epoxy is then added around each contact pin 422 and around the orifice end 433. The assembly is then baked in a circulating air oven at 65°C. for one hour.

The filter 300 is formed from a polyester mesh with 30 um pores and positioned in a polypropylene

housing. The air pressure supplied to the reservoir 200 during continuous printing operations is regulated at approximately 10 to 30 psi.

The reagents used have the following characteristics:

Printing (drop on demand mode):

5 Fluid viscosity range: 1 - 30 centipoises

Fluid surface tension: 20 - 70 dyne/cm

Printing (continuous mode):

Fluid viscosity range: up to 50 centipoises

Fluid surface tension: not measured

10 Dispensing (drop on demand mode):

Fluid viscosity range: 2 - 30 centipoises

Fluid surface tension: 20 - 70 dyne/cm

15 A measure of the performance and selected operating characteristics for a typical jetting head are presented in Figs. 9-11. Fig. 9 is a graph of the mass of a droplet as a function of droplet emission frequency for three fluids. The viscosity of the fluids were 1, 5 and 24 centipoise and the transducer excitation pulse width was 35 microseconds. As shown in Fig. 9, the higher fluid viscosity results in a more stable operating performance of the jetting head. Fig. 10 is a graph of droplet velocity as a function of droplet emission frequency for fluid viscosities of 1, 5 and 24 centipoise. The log of the total fluid weight as a function of the log of the number of droplets emitted is shown in Fig. 11. The fluid used has a viscosity of 2 centipoise, a surface tension of 20 dynes/cm, and a density of .8 grams/cc. The transducer excitation pulse was 80 volts and the excitation frequency was approximately 711 Hz.

20 Some blood typing reagents and some allergen reagents have very low viscosities and surface tensions. Although in some cases viscosity modifiers, such as glycerol, dextran, glucose, and the like, may be added to increase the viscosity, a few reagents are adversely affected by such modifiers.

25 Developing stable and reproducible demand mode jetting is difficult with very low viscosities. Although droplet emission can be established at some fundamental frequencies, the droplets dispensed may have small satellite droplets which reduce the accuracy for metering and dispensing applications. However, even with the satellite drops, sufficient reagent is adequately delivered for most print applications without a substantial decrease in print quality.

30 Glycerin may be used as a viscosity modifier to improve jetting reliability and to prevent obstruction of the orifice arising from evaporation of the reagent fluid components. Glycerin has been found especially beneficial for those reagents containing particulate material. The evaporation of the fluid component results in a concentration of glycerin located at the orifice. The plug of glycerin substantially prevents further evaporation of the reagent fluid. During the next activation cycle of the transducer, the plug of glycerin is 35 expelled from the orifice.

When operating in the dispensing mode the volume of the droplets can be varied to substantially uniformly contain from 100 pico-liters to 1 micro-liter. The droplets can be produced at a rate of approximately 1 khz to 8 khz. When operating in the printing mode the size of the pel made by each droplet measures approximately .001-.012 inches in diameter.

40 A copy of the program used in the computer 700 for a printing operation is attached hereto as Appendix A. The values, manufacturer and manufacturing part number of the circuit components of the jetting control unit 500 are substantially as follows:

5

	<u>Ref. Numeral of Component</u>	<u>Description and Value</u>	<u>Manufacturer and Part No.</u>
10	R39, 45-48, 57, 58	RES. 10KOHM, WATT5% C. F.	
	R66	RES. 1500HM, WATT5% C. F.	
	R3	RES. 15KOHM, WATT5% C. F.	
15	R34	RES. 16KOHM, WATT5% C. F.	
	R50	RES. 2.4KOHM, WATT1% M. F.	
	R13, 23, 36, 40, 41	RES. 2.4KOHM, WATT5% C. F.	DALE RLO79242G
20	R56	RES. 20KOHM, WATT5% C. F.	
	R8	RES. 2200HM, WATT5% C. F.	
	R6	RES. 270HM, WATT5% C. F.	
	R7, 12, 25	RES. 2KOHM, WATT5% C. F.	
25	R67	RES. 3.6KOHM, WATT5% C. F.	
	R51, 53	RES. 3.9KOHM, WATT5% C. F.	
	R29	RES. 300KOHM, WATT5% C. F.	
	R61	RES. 30KOHM, WATT1% C. F.	
	R15-18, 26-28, 54, 55, 64	RES. 4.7KOHM, WATT5% C. F.	
30	R62	RES. 45.3KOHM, WATT1% M. F.	DALE RN55D4532F
	R30, 33	RES. 470HM, WATT5% C. F.	
	R21	RES. 4700HM, WATT5% C. F.	
	R19	RES. 47KOHM, WATT5% C. F.	
	R35	RES. 5100HM, WATT5% C. F.	
35	R43	RES. 5.2KOHM, WATT5% C. F.	
	R60	RES. 7.5KOHM, WATT5% C. F.	
	R37	RES. 75KOHM, WATT5% C. F.	
	R9	RES. 76KOHM, WATT1% M. F.	
	R11	RES. 8200HM, WATT5% C. F.	
40	U2, 11, 14, 16, 22	RES. DIP NETWRK. 47KOHM	
	C21, 41, 45	CAP. AXIAL1MM@250VDC	
	C24	CAP. AXIAL220MF@250VDC	
	C10	CAP. AXIAL ALUM ELEC. 4700 OMF@25VDC	
45	C1, 2, 3, 55, 60	CAP. RADIAL DIPPED TANT. 10MF@25VDC	MALLORY TCG472U025N1C
	C53	CAP. RADIAL DIPPED TANT. 1MF@35VDC	KEMET T350E106M025AS
50	C36	CAP. RADIAL DIPPED TANT. 47MF@10VDC	KEMET T350A105K035AS
			T350H566MC10AS

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<u>Ref. Numeral of Component</u>	<u>Description and Value</u>	<u>Manufacturer and Part No.</u>
C54	CAP. RADIAL SILV MICA 100PF300VDC	KAHGAN SD5101J301
C57	CAP. RADIAL SILV MICA 20PF300VDC	KAHGAN SP12200J301
<sup>10</sup> C49	CAP. RADIAL SILV. MICA 39PF300VDC	KAHGAN SP12390J301
C39	CAP. RADIAL X7R MLC .015MF@50VDC	KEMET C315C102K1R5CA
<sup>15</sup> C6	CAP. RADIAL X7R MLC .022MF@50VDC	KEMET C315C223K5R5CA
C30,35,37	CAP. RADIAL 25U MLC .015MF@50VDC	KEMET C315C153K5R5CA
C4,7	CAP. RADIAL 25U MLC .01MF@50VDC	KEMET C315C103K5R5CA
<sup>20</sup> C4,5,6,9,11-19, 22,23,25-28	CAP. RADIAL 25U MLC .22MF@50VDC	KEMET C322C224M5U5CA
C31-34,37,42,43 47,48,50-52		
<sup>25</sup> C56,58,59		
C46	CAP. VARI. 2-12PF.	JOHANSEN #9626
CR7,8,9,10, 11,12,17	DIODE SIL.	ITT.FAIRCHILD.1N4148
<sup>30</sup> CR1,2,3,4	DIODE SIL. FAST	GENL. INST. EGP10D
CR5	DIODE SIL. FASTHIVOLT	GENL. INST. UF4007
CR6,13,15	DIODE SIL. REF.2,500VDC	NATL. SEMI-LM3852-2.5
CR14,16	DIODE SIL. ZENER3.6V.25WATT	MOTOROLA 1N4622A
U6,13,15,17	SWITCH 8 POSITION DIP	CTS 206-8
<sup>35</sup> Q2,9,12	TRANSTOR. COMMON NPN	MOTOROLA 2N2222A
Q8,10,11	TRANSTOR. COMMON PNP	MOTOROLA 2N2907A
Q4	TRANSTOR. HIVOLTHIFREQ. NPN	MOTOROLA MPSU10
Q7	TRANSTOR. HIVOLTHIFREQ. PNP	MOTOROLA MPSU60
Q1	TRANSTOR. HIVOLTHIINPN	TI, MOTOROLA TIP48
<sup>40</sup> Q3,14	TRANSTOR. HIVOLTPNP2N3439	MOTOROLA 2N3439
Q13	TRANSTOR. HIVOLTPNP	MOTOROLA MJE5731
U5,27	IC 1-SHOT 74HC221	NATL. SEMI MM74HC221N
U23,26	IC 1-SHOT 74LS221	NATL. SEMI DM741S221N
U7-10	IC COMPARATOR 74HC688	NATL. SEMI MM74HC688N
<sup>45</sup> U30	IC CONVERTER DAC0800	NATL. SEMI DAC0800LCN
U24,25	IC COUNTER 74HC193	NATL. SEMI MM74HC193N
U28	IC HI SLEW HI VOLT OP AMP	BURR-BROWN 3584JM
U1	IC HYBRID DC/DC CONVERTER	BURR-BROWN MODEL 724
U4	IC OC DRIVER SN7406	NATL. SEMI DM7406N
<sup>50</sup> U3	IC OCTAL LATCH 74HC374	NATL. MM74HC374N
U12,29,31,32	IC OP AMP LF256	NATL. SEMI LF256H
U18,19,20,21	IC OPTO ISOLATOR	HEWLT-PCRD HCPL2300
R24,42,63	POT100KOHM $\frac{1}{2}$ WATT10%	BOURNS 3622-1-104
R38,49,52	POT10KOHM $\frac{1}{2}$ WATT10%	BOURNS 3622W-1-103
R20	POT25KOHM $\frac{1}{2}$ WATT10%	BOURNS 3622W-1-253
<sup>55</sup> R14,31	POT2KOHM $\frac{1}{2}$ WATT10%	BOURNS 3622W-1-202

<u>Ref. Numeral of Component</u>	<u>Description and Value</u>	<u>Manufacturer and Part No.</u>
5 VRI	REGULATOR 5VDC	
R10	RES. 1MEGOMH, WATT5%C. F.	NATL. LM340T-5.0
R2, 4	RES. 1.2KOHM, WATT5%C. F.	
R32	RES. 1.6KOHM, WATT5%C. F.	
R44	RES. 1.8KOHM, WATT5%C. F.	
10 R1	RES. 10MEGOMH, WATT5%C. F.	
R5, R22	RES. 100OMH, WATT5%C. F.	
R65	RES. 100KOHM, WATT5%C. F.	
R59	RES. 1OKOHM, WATT1%C. F.	DALE RN55D1002F
R100	RES. 2700HM	
15 R101, 108	RES. 4700HM	
R102, 103	RES. 1KOHM	
106, 109, 110		
R104	RES. 47000HM	
R105	PCT. 100KOHM	
R107	POT. 10KOHM	
20 R111, 113	RES. 2200HM	
R112	RES. 22CHM	
R114, 115	RES. 470HM	
C100	CAP. 10MF035 VPC	
C108	CAP. 10000 PF	
25 D100	DIODE	1N4148
Q100, 105	TRANSTOR	2N2222
Q101, 102	TRANSTOR	2N3906
Q103, 104	TRANSTOR	2N3904
30 U100, U108	IC I-SHOT	74LS123
U103, 104	IC INVERTOR	74LS04
105, 106		
U108	IC LINE DECODER	74LS138

Of course, it should be understood that a wide range of changes and modifications can be made to the preferred embodiments described above. For example, the transducer could be of a type other than piezoelectric such as magneto-strictive, electro-strictive, and electro-mechanical. It is therefore intended that the foregoing detailed description be regarded as illustrative rather than limiting, and that it be understood that it is the following claims, including all equivalents, which are intended to define the scope of this invention.

40 APPENDIX

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5 Reagent Jet Printer  
Reagent Calibration

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Reagent Jet Printer  
 Reagent Calibration

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IBM Personal Computer BASIC Compiler V2.00

Offset	Data	Source Line	
25	0080 020A	IF AS = CHR\$(13) THEN TYPEI = 1: 'execute (cr)	
	00CA 020A	IF AS = "+" THEN TYPEI = 2: 'increasest variable	
	00E0 020A	IF AS = "-" THEN TYPEI = 3: 'decreasest variable	
	00F6 020A	IF AS = CHR\$(65) + CHR\$(80) THEN TYPEI = 4: 'up arrow key	
	011B 020A	IF AS = CHR\$(65) + CHR\$(80) THEN TYPEI = 5: 'down arrow key	
	0140 020A	IF AS = CHR\$(65) + CHR\$(73) THEN TYPEI = 6: 'left arrow key	
30	0145 020A	IF AS = CHR\$(65) + CHR\$(77) THEN TYPEI = 7: 'right arrow key	
	018A 020A	IF AS > CHR\$(47) AND AS < CHR\$(123) THEN TYPEI = 8: 'ascii 0 - z	
	01C2 020A	ON TYPEI GOSUB T1, T2, T3, T4, T5, T6, T7, T8	
	01D8 020A	END	
35	01DB 020A	TYPEI = 0	
	01E6 020A	EXIT SUB	
	01EA 020A	REM SPASE	

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5 Reagent Jet Printer  
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TZX Personal Computer BASIC Compiler V2.00

Offset	Data	Source Line
10	01EA	0203 'REAGENT.JET PRINT SUBROUTINES FOR THIS MODULE 010000000000
	01EA	0204
	01EA	0204
	01EF	0204 T1: '(cr) execute command
	0205	0204 IF NEXUS(12,0) < 12 THEN TYPE1 = 0:RETURN: 'exit to print menu, no action
	0214	0205 ON NEXUS - 11 GOSUB T1A, T1B, T1C, T1D
	0220	0206 IF NEXUS(13,0) < 15 THEN TYPE1 = 0
15	0220	0206 RETURN.
	0230	0206
	0230	0206 T1A: 'start/stop drop flow
	0235	0206 IF NEXUS(12,0) = "START" THEN GOSUB START.IKK
	0250	0206 IF NEXUS(12,0) = "STOP" THEN GOSUB STOP.IKK
	027F	0206 NEXUS(12,0) = TEMP\$
20	027A	0210 COLOR 0,7:GOSUB 01SPRNMU
	02AC	0210 RETURN
	02B0	0210
	02B0	0210
	02B5	0210 START.IKK:
	02B5	0210 TEMP\$ = "STOP"
	02BF	0210 CALL DOT,ON: 'in module PCI
25	02C0	0210 LOCATE 17,71:COLOR 27,0:PRINT "PRINTING";
	02F1	0210 ACTIVE1 = 1
	02F8	0210 RETURN
	02FC	0210
	02FC	0210 STOP.IKK:
	0301	0210 TEMP\$ = "START"
30	0303	0210 CALL DOT,OFF: 'in module PCI
	0317	0210 LOCATE 17,71:COLOR 15,0:PRINT " ";
	0330	0210 ACTIVE1 = 0
	0344	0210 RETURN
	0348	0210
	0348	0210 T1B: 'load reagent profile
35	0349	0210 IF NEXUS(6,1) = "" THEN LOCATE 25,1:PRINT "Reagent Name is not specified";:GOSUB ANYKEY:RETURN
	0351	0210
	0351	0210 GOSUB SEARCH
	0357	0210
	0357	0210 IF IZ < (REANUM1 + 1) THEN GOTO FOUND
	0358	0210 LOCATE 25,10-LEN(NEXUS(6,1))/2:PRINT NEXUS(6,1);" not Found";
40	0401	0214 GOSUB ANYKEY: 'wait for a keybit
	0404	0214 RETURN
	040E	0214
	040E	0214
	0413	0214 FOUND:
	0413	0214 FILES = RIGHTS\$(STR\$(IZ),LEN(STR\$(IZ))-1) + "REA.BJP"
	0437	0218 OPEN FILES FOR INPUT AS 01: 'set pattern data file for read
45	0448	0218 INPUT #1,NEXUS(0,0): 'read frequency
	0448	0218 INPUT #1,NEXUS(1,0): 'read amplitude
	0483	0218 INPUT #1,NEXUS(2,0): 'read strobe delay
	04AE	0218 INPUT #1,NEXUS(3,0): 'read pulse width
	04B1	0218 INPUT #1,NEXUS(4,0): 'read rise time
	04F4	0218 INPUT #1,NEXUS(5,0): 'read fall time
50	0519	0218
	0519	0218 INPUT #1,NEXUS(7,1): 'read concentration
	0530	0218 INPUT #1,NEXUS(8,1): 'read density
	0541	0218 INPUT #1,NEXUS(9,1): 'read viscosity
	0553	0218 INPUT #1,NEXUS(10,1): 'read surface tension
55	05A7	0218

6 Reagent Jet Printer  
Reagent Calibration

Offset	Data	Source Line
05A7	0218	CLOSE #1: 'done with data file
10 05B0	0218	OPEN "SEADEF.RJP" FOR OUTPUT AS #1
05B1	0218	PRINT #1,FTLES: 'save filenames in default file
05C2	0218	PRINT #1,REAMUN(6,1): 'save the directory name as well
05D2	0218	CLOSE #1
05F4	0218	GOSUB DISP.PARMS: 'show all parameters
15 0601	0218	RETURN
0605	0218	TIC: 'save reagent profile
0605 0608	0218	IF REAMUN(6,1) = "" THEN LOCATE 25,1:PRINT "Reagent Name is not specified";:GOSUB ANKEY:RETURN
0614	0218	OPEN "READIR.RJP" FOR INPUT AS #1
064E	0218	INPUT #1,REAMUN
065F	0218	CLOSE #1
20 0671	0218	IF REAMUN < 80 THEN GOTO SAVE.REA
0678	0218	LOCATE 25,1:PRINT "Directory is Full (80 reagents max.)"
0687	0218	GOSUB ANKEY:RETURN
06A1	0218	SAVE.REA:
06A8	0218	GOSUB SEARCH
06B0	0218	IF #1 > REAMUN THEN GOTO SAVEREA1
06C7	0218	REAMUN = #1
06CE	0218	COLOR 15,0
06DA	0218	LOCATE 25,1:PRINT REAMUN(6,1);" already exists. Replace it with new values? "
070C	0218	AS = ""
0716	0218	WHILE AS = ""
0725	0218	AS = INKEY\$
072F	0218	WEND
0732	0218	LOCATE 25,1:PRINT SPACES(73);
074F	0218	IF AS = "Y" OR AS = "y" THEN GOTO REPLACE
0778	0218	RETURN
077C	0218	SAVEREA1:
077C 0781	0218	KILL "READIR.OLD": 'delete old backup directory
0788	0218	NAME "READIR.RJP" AS "READIR.OLD": 'save old directory
0792	0218	OPEN "READIR.OLD" FOR INPUT AS #1
07A3	0218	OPEN "READIR.RJP" FOR OUTPUT AS #2: 'set up new dir
40 07B3	0218	INPUT #1,REAMUN: 'read number of dir entries
07B5	0218	REAMUN = REAMUN + 1: 'increase by 1
07C7	0218	WRITE #2,REAMUN: 'save in new directory
07D9	0218	FOR I=1 TO REAMUN - 1
07E1	0218	LINE INPUT #1,AS: 'read entry from old dir
45 07F4	021C	PRINT #2,AS: 'write entry in new directory
0807	021C	NEXT I
0817	021C	CLOSE #1
0832	0220	PRINT #2,REAMUN(6,1): 'write new entry to new directory
0833	0220	CLOSE #2: 'done with directory
50 0839	0220	REPLACE:
0858	0220	FILES = RIGHTS(STR\$(REAMUN),LEN(STR\$(REAMUN))-1) + "REA.RJP"
0862	0220	
0862	0220	
0867	0220	
0888	0220	

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Offset	Data	Source Line
10	08E9	OPEN #FILE\$ FOR OUTPUT AS #1: 'create new pattern data file
	0220	WRITE #1,RENU(0,0): 'store frequency
	08E9	WRITE #1,RENU(1,0): 'store amplitude
	0220	WRITE #1,RENU(2,0): 'store strobe delay
	08E9	WRITE #1,RENU(3,0): 'store pulse width
	0220	WRITE #1,RENU(4,0): 'store rise time
	091E	WRITE #1,RENU(5,0): 'store fall time
15	093F	WRITE #1,RENU(6,0): 'store concentration
	0220	WRITE #1,RENU(7,0): 'store density
	0940	WRITE #1,RENU(8,0): 'store viscosity
	0220	WRITE #1,RENU(9,0): 'store surface tension
20	09EA	CLOSE #1: 'done with data file
	0220	
	09F1	
	0220	
	09F1	
	0220	
	0A03	
	0220	
	0A13	OPEN 'READDEF.RJP' FOR OUTPUT AS #1: 'save filename in default file
	0220	PRINT #1,FILE\$:
25	0A33	PRINT #1,RENU(6,1): 'save the directory name as well
	0220	CLOSE #1:
	0A3C	RETURN
	0A40	
	0220	
	0A45	
	0220	
30	0A56	INPUT #1,RENUMUL: 'read number of patterns in dir
	0220	II = 1: 'set entry pointer
	0A5F	
	0220	
	0A74	
	0220	
	0A81	
	0220	
	0A85	
35	0A9E	OPEN 'READIR.RJP' FOR INPUT AS #1: 'read next pattern base from dir
	0220	IF AT = RENUMUL THEN GOTO SEARCH.DONE: 'compare name with dir entry
	0A9F	II = II + 1
	0220	IF II < (RENUMUL + 1) THEN GOTO SLOOP: 'check for done'
	0A9E	
	0220	
	0A9F	
	0220	
	0A9E	SEARCH.DONE:
	0220	CLOSE #1:
	0A9F	RETURN
	0220	
40	0A91	T1: 'return with no change to exit reagent calibrate
	0220	PRINT #3,""
	0A96	CLOSE #3: 'close com channel
	0220	RETURN
	0A9E	
	0220	
	0A9F	
45	0A91	T2: 'process "+" key
	0220	IF RENU > 5 THEN RETURN
	0A96	NEWTIME = TIMER
	0220	DELTA TIME = NEWTIME - OLDTIME
	0B0F	OLDTIME = NEWTIME
	0224	IF DELTA TIME > 0.15 THEN MULTI = 1 ELSE MULTI = MULTI + 1
	0B1F	IF MULTI > 100 THEN MULTI = 100
	0226	RENU(REDNU,0) = RENU(REDNU,0) + RENU(REDNU,3) * MULTI: 'add increment'
	0B29	IF RENU(REDNU,0) > RENU(REDNU,1) THEN RENU(REDNU,0) = RENU(REDNU,1): 'check max value'
	0B48	COLOR 15,1:gosub DISPLAY:RETURN 'show new value'
50	0B51	
	0226	
	0B5F	
	0226	
	0C06	
	0226	
	0C1D	
	0226	
	0C1D	
	0226	
	0C22	
55	0C51	T3: 'process "-" key
	0226	IF RENU > 5 THEN RETURN
	0C1D	NEWTIME = TIMER

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Offset	Data	Source Line
10	0C18 022E	DELTATIME = DOWNTIME - OLDTIME
	0C48 022E	OLDTIME = KEYTIME
	0C53 022E	IF DELTATIME > 0.15 THEN MULT1 = 1 ELSE MULT1 = MULT2 + 1
	0C77 022E	IF MULT1 > 100 THEN MULT1 = 100
	0C89 022E	RENU(KEWUI,0) = RENU(KEWUI,0) + RENU(KEWUI,3) * MULT1: 'sub increment
	0C98 022E	IF RENU(KEWUI,0) < RENU(KEWUI,2) THEN RENU(KEWUI,0) = RENU(KEWUI,2): 'check min value
15	0D32 022E	COLOR 15,1:GOSUB DISPLAY:RETURN: 'show new value
	0D49 022E	
	0D49 022E T4:	'process up arrow key
	0D4E 022E	IF KEWUI MOD 6 = 0 THEN RETURN: 'is top row already
	0D63 022E	DIFF1 = -1:GOSUB KEYMENU:RETURN: 'move pointer up one
	0D74 0230	
20	0D74 0230	T5: 'process down arrow key
	0D79 0230	IF KEWUI MOD 6 = 5 THEN RETURN: 'is bottom row already
	0D8F 0230	DIFF1 = 1:GOSUB KEYMENU:RETURN: 'move pointer down one
	0D90 0230	
	0DA0 0230	T6: 'process left arrow key
	0D45 0230	IF INT(KEWUI / 6) = 0 THEN RETURN: 'is left column already
25	0D85 0230	DIFF1 = -6:GOSUB KEYMENU:RETURN: 'move pointer one left
	0D96 0230	
	0D96 0230 T7:	'process right arrow key
	0D9B 0230	IF INT(KEWUI / 6) = 2 THEN RETURN: 'is right column already
	0D9E 0230	DIFF1 = 6:GOSUB KEYMENU:RETURN: 'move pointer one right
	0EOF 0230	
30	0EOF 0230 T8:	'input keys into KEYBUFS until (cr) is entered
	0E14 0230	IF KEWUI > 10 THEN RETURN
	0E23 0230	LOCATE 25,30:COLOR 31,0:PRINT "ENTER KEY VALUE":COLOR 15,0
	0E35 0230	KEYBUFS = AS
	0E5F 0234	WHILE AS <> CHR\$(13)
	0E72 0234	LOCATE 25,47:PRINT SPACES(13);
35	0E8F 0234	LOCATE 25,47:PRINT KEYBUFS;
	0E94 0234	AS = ""
	0E93 0234	WHILE AS = ""
	0E92 0234	AS = INKEY\$
	0ECC 0234	IF ACTIVE1 = 1 AND DOWNTIME < TIMER THEN GOSUB PEN.DOWN
	0E96 0234	WEND
40	0E99 0234	IF AS = CHR\$(10) AND LEN(KEYBUFS) > 0 THEN KEYBUFS = LEFT\$(KEYBUFS,LEN(KEYBUFS)-1)
	0F3B 0234	IF AS = CHR\$(13) AND LEN(KEYBUFS) < 15 THEN KEYBUFS = KEYBUFS + AS
	0F73 0234	WEND
	0F79 0234	
	0F79 0234	IF KEWUI > 5 THEN GOTO STORESTRING
45	0F88 0234	TEMP = VAL(KEYBUFS) 'temp has value of keys input
	0F98 0238	
	0F98 0238	'round off temp according to step size in scale array
	0F98 0238	TEMP = INT(TEMP / (RENU(KEWUI,3)) + .5) * RENU(KEWUI,3)
	0FD1 0238	
50	0FD1 0238	'test TEMP for maximum and minimum values in scale array
	0FD1 0238	IF TEMP > RENU(KEWUI,1) THEN TEMP = RENU(KEWUI,1)
	1019 0238	IF TEMP < RENU(KEWUI,2) THEN TEMP = RENU(KEWUI,2)
	104F 0238	
	104F 0238	'insert new value into scale array and update screen
	104F 0238	RENU(KEWUI,0) = TEMP
55	1068 0238	LOCATE 25,30:PRINT SPACES(40);

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Offset	Data	Source Line
10	0238	COLOR 0,7:GOSUB DISPLAY
104A	0238	RETURN
104E	0238	
105E	0238	STOKESTRINGS:
1043	0238	MEMU\$(MEMU\$,1) = KEYBUF\$
108F	0238	LOCATE 23,30:PRINT SPACES\$(40);
108C	0238	COLOR 0,7:GOSUB DISPLAY
10EE	0238	RETURN
10F2	0238	
10F2	0238	PELDOZ:
10F7	0238	DOWTIME = TIMER + 1
1107	0238	PRINT B3,"";
20	1117	RETURN
1118	0238	
1118	0238	ANYKEY:
1120	0238	LOCATE 23,64:PRINT "Strate any key..";
113A	0238	AS = "
1144	0238	WHILE AS = "
25	1153	AS = INKEY\$
115D	0238	KEY
1160	0238	LOCATE 23,1:COLOR 15,0:PRINT SPACES\$(79);:COLOR 15,1
1196	0238	RETURN
119A	0238	
119A	0238	NEWMENU: 'write old item in yellow, point to and highlight new item
30	119F	COLOR 14,0:GOSUB DISPLAY
119I	0238	MEMU1 = MEMU\$ + DIFF\$
119D	0238	IF MEMU1 = 11 THEN MEMU1 = 10
11CF	0238	IF MEMU1 > 15 THEN MEMU1 = 15
11E1	0238	COLOR 0,7:GOSUB DISPLAY:RETURN
11F7	0238	
35	11F7	INITIALIZE:
11FC	0238	'change to second screen and display messages
11FC	0238	SCREX 0,0,1,1:COLOR 7,0:CLS:LOCATE 10,28:PRINT "Initializing Mem Display";
1240	0238	LOCATE 12,33:PRINT "Please Wait...";
125A	0238	
125A	0238	'initialize variables
40	125A	ACTIVE1 = 0: ' not printing
125A	0238	
1261	0238	'initialize plotter com channel
1261	0238	
1261	0238	OPEN "COM1:2400,N,8,2" AS B3
45	1273	PRINT B3,":UECS,EPV1,R";
1283	0238	
1283	0238	'initialize digital port
1283	0238	SDIZ = 4
1283	0238	CALL DIGITAL.OUT(SCRI)
128A	023A	
50	127A	SDIZ = 0
12A1	023A	CALL DIGITAL.OUT(SCRZ); 'pulse reset line to set amplitude to 0V.
12B1	023A	SDIZ = 4
12B1	023A	CALL DIGITAL.OUT(SCRZ)
12C8	023A	
12C8	023A	'set hardware pulse width
55	12C8	CALL SET.DOT.WIDTH(5) 'in module PCI

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1. INTRODUCTION

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Offset	Data	Source Line
25	1814 0244	DISP.PARMS1
	1817 0244	'display 18 menu choices in yellow
	1819 0244	
	1817 0244	COLOR 14,0
	1825 0244	FOR MENU1 = 0 TO 17
30	1828 0244	GOSUB DISPMENU
	1831 0244	NEXT MENU1
	1841 0244	
	1841 0244	'set for reagent name and highlight it
	1841 0244	MENU1 = .6:COLOR 0,7
	1854 0244	GOSUB DISPMENU
35	185A 0244	
	185A 0244	SCREEN 0,0,0,0
	186F 0244	RETURN
	1873 0244	REM SPAGE

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10 Offset Data Source Line

1873 0244 DISPLAY:  
1876 0244 LOCATE (RENU1 MOD 6)+2+7,(INT(RENUI/6)+28+2)+15+INT(RENUI/12)  
1884 0244 PRINT RENU1(RENUI,0)  
18F2 0244 IF RENU1 > 5 THEN GOTO SHOWSTRING: ' as value to display  
1901 0244 LOCATE (RENUI MOD 6)+2+7,RENUI(RENUI,4)  
1933 0244 PRINT USING RENU1(RENUI,1);RENUI(RENUI,0);  
1966 0244 IF RENU1 > 2 THEN RETURN  
1975 0244 ON RENU1+6000 SET.FREQ, SET.AMP, SET.DELAY  
1986 0244 RETURN

20 198A 0244 SHOWSTRING:  
1987 0244 IF RENU1 > 10 THEN RETURN  
199E 0244 LOCATE (RENUI MOD 6)+2+7,48  
198A 0244 PRINT ''  
19C7 0244 LOCATE (RENUI MOD 6)+2+7,48  
19E3 0244 PRINT RENU1(RENUI,1)  
1A02 0244 RETURN

25 1A06 0244  
1A06 0244  
1A0B 0244  
1A24 0244  
1A34 0244  
30 1A57 0246  
1A69 0246  
1A89 0246  
1A99 0246  
1A9D 0246  
1A9D 0246  
35 1AA2 0246  
1ACB 0246  
1ADC 0246  
1AE8 0248  
1AEF 0248  
1AF6 0248  
40 1B08 0248  
1B15 0248  
1B22 024C  
1B3F 024C  
1B4F 024C  
1B6F 024C  
45 1B7F 024C  
1B91 024C  
1B95 024C  
1B95 024C  
1B9A 024C  
1B96 024C  
50 1B9C 024C  
1B9A 024C  
1B9A 024C  
REX SPASE

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SET.FREQ:  
TEMP = RENU1(RENUI,0)  
CALL SET.DOT.RATE(TEMP); 'in module PCI  
LED1 = J-INT((TEMP+500)/1000)  
IF LED1 < 0 THEN LED1 = 0  
SCR1 = 4 + (LED1 + J2); 'set LED intensity  
CALL DIGITAL.OUT(SCR1); 'in module PCI  
RETURN

SET.AMP:  
SCR1 = CINT(RENUI(RENUI,0) + J3 / 150); 'convert volts to binary number  
IF SCR1 = OLD.AMP.VALUE1 THEN RETURN  
TEMP1 = SCR1 - OLD.AMP.VALUE1; 'calculate delta  
OLD.AMP.VALUE1 = SCR1; 'update old value to current value  
DIG.VAL1 = 6  
IF TEMP1 < 0 THEN DIG.VAL1 = 5  
TEMP1 = ABS(TEMP1)  
FOR J2 = 1 TO TEMP1  
SCR1 = DIG.VAL1 + (J2\*LED1)  
CALL DIGITAL.OUT(SCR1); 'pulse higher or lower  
SCR1 = 4 + (J2 + LED1)  
CALL DIGITAL.OUT(SCR1); 'set port to normal  
NEXT J2  
RETURN

SET.DELAY:  
TEMP = RENU1(2,0)  
CALL SET.STROBE.DELAY(TEMP); 'in module PCI  
RETURN

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jet Jet Printer  
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Offset	Data	Source Line
IBCA	024C	'***** DATA USED BY THIS MODULE *****
IBCA	024C	
75	IBCA	ARCDATA:
	IBCF	DATA "Frequency" Hz",",111",10000,1,1,16
	IBD1	DATA "Amplitude" V",",111",150,0,1,19
	IBD3	DATA "Stroke Delay" #5",",111,111,0,15999.5,5,5,16
	IBD5	DATA "Pulse Width" ",",111,111,0,1,19
	IBD7	DATA "Rise Time" ",",111,111,0,1,19
20	IBD9	DATA "Fall Time" ",",111,111,0,1,19
	IBD8	DATA "Mass",",0,0,0,0
	IBD9	DATA "Concentration",",0,0,0,0
	IBDF	DATA "Density",",0,0,0,0
	IBE1	DATA "Viscosity",",0,0,0,0
	IBE3	DATA "Surface Tension",",0,0,0,0
25	IBE5	DATA ",",0,0,0,0
	IBE7	DATA "START",",0,0,0,0
	IBE9	DATA "LOAD",",0,0,0,0
	IBE9	DATA "SAVE",",0,0,0,0
	IBE9	DATA "EXIT",",0,0,0,0
	IBEF	DATA ",",0,0,0,0
30	IBF1	DATA ",",0,0,0,0
	IBF3	
	IBF3	TABLE:
	IBFB	DATA 3,1,218
	IBFA	DATA 3,29,210
	IBFC	DATA 3,69,210
35	IBFE	DATA 3,80,191
	IC00	DATA 3,1,198
	IC02	DATA 5,29,206
	IC04	DATA 5,69,206
	IC06	DATA 5,80,193
	IC08	DATA 19,1,192
40	IC0A	DATA 19,29,208
	IC0C	DATA 19,69,208
	IC0E	DATA 19,80,217
	IC10	
	IC10	END SUB
	IC17	
45	IC17	
	2SEB-	024C
		50426 Bytes Available
		43960 Bytes Free
50		0 Warning Error(s)
		0 Severe Error(s)

Reprint Set Printed

### **Pattern Entry/Modification**

Offset Data Source Line IBM Personal Computer BASIC Compiler V2.00

0030 0006 REM STITLE: 'Reagent Jet Printer' \$SUBTITLE: 'Pattern Entry/Modification'  
 0030 0006 'MODULE - "PATENT" Pattern creation, modification, and filing  
 0030 0006  
 0030 0006 'AUTHOR - W. A. Enevold  
 0030 0006  
 0030 0006 'COPYRIGHT (C) 1985 ABBOTT LABORATORIES  
 0030 0006  
 10 0030 0006 'REVISION - 1.2 03-10-86 WAE Remove Mouse inputs  
 0030 0006 ' 1.1 02-20-86 WAE Add 80 pattern limit to save  
 0030 0006 ' 1.0 01-13-86 WAE Creation of initial code  
 0030 0006  
 15 0030 0006  
 0030 0006 'SYSTEM - This code can only be compiled by the BASCOM  
 0030 0006 ' COMPILER, it will not run under the INTERPRETER!!  
 0030 0006  
 20 0030 0006  
 0030 0006 'DESCRIPTION:  
 0030 0006 ' This module allows the user to LOAD, SAVE, DIRectory, D  
 0030 0006 ' RAW and  
 25 0030 0006 ' enter repeat count and other parameters for a pattern to  
 0030 0006 ' be printed.  
 0030 0006 ' The low-resolution graphics mode is selected and a menu  
 0030 0006 ' is displayed  
 0030 0006 ' across the bottom of the screen. Using arrow keys  
 0030 0006 ' point to the action to be taken and then invoke that ac  
 30 0030 0006 ' tion with the  
 0030 0006 ' Enter key. In the DRAW mode, another menu is  
 0030 0006 ' displayed which allows the user to select from LINE, RE  
 0030 0006 'CTangle,  
 35 0030 0006 ' Solid RECTangle, or CIRCLE pattern elements.  
 0030 0006  
 0030 0006  
 0030 0006 'DATA DICTIONARY  
 0030 0006 ' SCNDATL(50,5) 51 Row (Elements) by 6 Column array f  
 0030 0006 'or storing pattern elements  
 0030 0006  
 40 0030 0006 ' CURSOR(9) Storage for cursor graphics icon  
 0030 0006 ' MENUS(6) Up to 7 menu names can be saved here  
 0030 0006 ' ELNUMIZ Count of number of elements in a patt  
 0030 0006 'ers  
 0030 0006 ' II YI Current location of graphics cursor  
 0030 0006 ' GRID Value of one dot space on the screen  
 45 0030 0006 ' (default is 0.003')  
 0030 0006 ' ROWZ COLZ Location to print instructions  
 0030 0006 ' AS Storage for single key-strokes or inp  
 0030 0006 'at strings  
 0030 0006 ' MENUMUN Which menu is being displayed (1 or 2  
 0030 0006 ' )  
 0030 0006 ' ITEM Pointer to which menu item is highlig  
 0030 0006 ' hted (0 - 6)  
 0030 0006 ' REPEATZ Number of times pattern is to be repe  
 0030 0006 ' ated when printed  
 0030 0006 ' IDIFF YOFF I and Y axis distance between the pri  
 0030 0006 ' nting of repeated patterns  
 0030 0006 ' ROWSP COLSP Row and Column spacing for printing a  
 50 0030 0006 ' ultiple sets of patterns

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Reagent Jel Printer Pattern Entry/Modification				PAGE 2 07-05-86 10:46:13
Offset	Data	Source Line	IBM Personal Computer BASIC Compiler V2.00	
20	0030 0006	' PATHNZ - Number of patterns stored in the pattern directory PATDIR.RJP		
	0030 0006	' DRWZ DCOLI Row and Column location to display di rectory entrys		
	0030 0006	' NAME\$ Pattern case to be LOADED or SAVED to directory		
25	0030 0006	' IZ JZ Counters used to LOAD or SAVE the ele ment data from/to pattern data file		
	0030 0006	' FILES Name of pattern data file		
	0030 0006	' TERPZ Which type of element is being drawn. 1 = Line 2 = Rectangle		
30	0030 0006	' 3 = Solid Rectangle 4 = Circle		
	0030 0006	' FLAG\$ Same as TERPZ above		
	0030 0006	' STARTMSG\$ ENDMSG\$ Message display for startpoint and en dpoint of element entry		
35	0030 0006	' X1Z Y1Z Starting cursor position for element being drawn		
	0030 0006	' DIZ DYI Delta I and Y values used to re-position cursor after arrow key		
40	0030 0006	' MAXITEM The highest number item in th e current menu display		
	0030 0006	' IS IE Starting and ending I position of the menu highlighting blue box		
	0030 0006	' RADIUSZ The calculated radius of a ci rcle to be displayed		
45	0030 0006	' REM \$PACE		

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Reagent Jet Printer  
 Pattern Entry/Modification  
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 10 Offset Data Source Line IBM Personal Computer BASIC Compiler V2.00

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    0030 0006 SUB PATENTRY STATIC
    0047 0006
    0047 0006 WIDTH 40:SCREEN 1:CLS
    15 005F 0006 DIM SCADATZ(50,5),CURSORZ(9),MENU$(6)
    0060 029A ELMNUZ = 0:IZ=0:YZ=0:BRID = 0.005
    007F 02A4
    007F 02A4 LINE (0,0)-(6,6),,B
    00A1 02A4 LINE (0,3)-(6,3),,B
    20 00C5 02A4 LINE (3,0)-(3,6),,B
    00E9 02A4 PRESET (3,3)
    00F3 02A4 SET (0,0)-(6,6),CURSORZ
    0116 02A4 CLS
    011D 02A4
    25 011D 02A4 LINE (0,0)-(319,190),,B
    0140 02A4
    0140 02A4 RESTORE INSTRUC
    0147 02A4 FOR I=1 TO 4
    0151 02A4 READ ROWZ,COLZ,A$
    30 0164 02AC LOCATE ROWZ,COLZ:PRINT A$;
    0180 02AC
    0198 02B0
    019B 02B0 FIRST:
    01A0 02B0
    35 01AA 02B4
    01B0 02B4
    01B0 02B4 ON ITEM + 1 GOTO PATDIR, PATLOAD, PATSAVE, PATDRAW, REP
    EAT, PATEIT
    01CD 02B8 GOTO FIRST
    40 01D0 02B8
    01D0 02B8
    01D0 02B8 REPEAT:
    01D5 02B8 GOSUB ITEMBOILERASE: 'erase blue box around DIR
    01DB 02B8 LOCATE 25,1:PRINT SPACES$(39); 'erase menu line
    01FB 02B8 LOCATE 25,1:INPUT;"Enter Repeat Count ",REPEATI
    45 0218 02B8 LOCATE 25,1:PRINT SPACES$(39); 'erase menu line
    0235 02B8 LOCATE 25,1:INPUT;"Enter X Axis Offset ",XOFF
    0255 02B8 LOCATE 25,1:PRINT SPACES$(39); 'erase menu line
    0272 02B8 LOCATE 25,1:INPUT;"Enter Y Axis Offset ",YOFF
    0292 02C2 GOTO FIRST
    50 0296 02C2 PATEIT:
    0298 02C2 WIDTH 80:SCREEN 0:CLS
    02B2 02C2 EXIT SUB
    02B6 02C2 REM $PAGE
  
```

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Reagent Jet Printer Pattern Entry/Modification					PAGE 4 07-05-86 10:46:13
Offset	Data	Source Line	IBM Personal Computer BASIC Compiler V2.00		
10	0286	02C2	PATDIR: 'list directory of patterns		
15	028B	02C2	60SUB ITEMEOIERSASE: 'erase blue box around DIR		
	02C1	02C2	LOCATE 25,1:PRINT SPACES(39); 'erase menu line		
	02E6	02C2	OPEN "PATDIR.RJP" FOR INPUT AS #1: 'open directory		
20		file			
	02EF	02C2	INPUT #1, PATHNUM: 'read number of patterns in directory		
25	0301	02C4	LINE (1,1)-(318,189),0,BF: 'erase graphics tablet		
	0326	02C4	I = 0: 'set counter		
	0330	02C4			
	0330	02C4	DISLOOP: 'set for next value		
30	0335	02C4	I = I + 1: 'set for next value		
	0344	02C4	IF I > PATHNUM THEN GOTO DIRExit: 'test for done		
	035B	02C4	IF INT((I-1)/44) <> (I-1)/44 THEN GOTO SHOWexit		
	0364	02C4	IF INT((I-1)/44) < I THEN GOTO SHOWexit		
	03A9	02C4			
35	03A9	02C4	LOCATE 25,1:PRINT "More to Display. Continue ? (Y or N)"		
	03C3	02C4	"; 'wait for Y or N response		
	03C9	02C4	GOSUB CORLOOP: 'if N then don't continue		
	03DC	02C4	RE		
40	03DC	02C4	LINE (1,1)-(318,189),0,BF: 'erase graphics tablet		
	0401	02C4			
	0401	02C4	SHOWexit: 'calculate row for display		
	0406	02C4	DROWZ = ((I - 1) MOD 22) + 2: 'calculate row for display		
45	0422	02C6	DCOLZ = 4: 'set column to 4		
	0429	02C8	IF ((I - 1) MOD 44) > 21 THEN DCOLZ = 23: 'reset column if necessary		
	044C	02C8			
	044C	02C8	LINE INPUT #1, AS: 'read next name from directory		
	0459	02C8	LOCATE DROWZ,DCOLZ:PRINT AS; 'PRINT NAME		
	0475	02C8	GOTO DISLOOP		
	0479	02C8			
	0479	02C8	DIRExit: 'terminate access to PATDIR.RJP		
50	047E	02C8	CLOSE #1: 'terminate access to PATDIR.RJP		
	0485	02C8	GOTO FIRST		
	0489	02C8			
	0489	02C8	REM SPAGE		

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Reagent Jet Printer  
Pattern Entry/Modification

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Offset	Bits	Source Line	IBM Personal Computer BASIC Compiler V2.00
	0489	02C2	FATLOAD:
	048E	02C8	60SUB ITEMGOIERASE: 'erase blue box around DIR
	0494	02C8	OPEN "PATDIR.RJP" FOR INPUT AS #1
	04A3	02C8	INPUT #1,PATHUMI: 'read number of patterns in dir
	04B7	02C8	60SUB GETNAME: 'prompt for and input pattern name
		asrt	
	04B0	02C8	LINE (1,1)-(318,189),0,BF: 'erase graphics tablet
	04E2	02C8	
	04E2	02C8	60SUB SEARCH
	04E8	02C8	
	04EB	02C8	IF IZ < (PATHUMI + 1) THEN GOTO FOUND
	04FC	02CA	LOCATE 10,16-(LEN(NAMES)/2):PRINT NAMES;" not Found";
	0531	02CE	LOCATE 12,14:PRINT "Strike Any Key"
	054B	02CE	60SUB ANYKEY: 'wait for a keyhit
	0551	02CE	GOTO FIRST
	0555	02CE	
	0555	02CE	FOUND:
	055A	02CE	FILES = RIGHTS\$(STR\$(IZ),LEN(STR\$(IZ))-1) + "PAT.RJP"
	057E	02D2	OPEN FILES FOR INPUT AS #1: 'set pattern data file
		for read	
	058F	02D2	INPUT #1,ELNUMI: 'read number of elements in pattern
		term	
	05A1	02D2	INPUT #1,GRID: 'read grid size
	05B3	02D2	INPUT #1,REPEATI: 'read repeat count
	05C5	02D2	INPUT #1,XOFF: 'read x axis offset for repeat
	05D7	02D2	INPUT #1,YOFF: 'read y axis offset for repeat
	05E9	02D2	
	05E9	02D2	FOR IZ = 0 TO ELNUMI - 1
			FOR JZ = 0 TO 5
	05F7	02D4	
	05FD	02D4	INPUT #1,SCREENIZ(IZ,JZ): 'read file into screen
		array	
	0621	02D6	NEXT JZ
	0631	02D6	NEXT IZ
	0643	02D6	CLOSE #1: 'done with data file
	064A	02D6	
	064A	02D6	OPEN "PATDEF.RJP" FOR OUTPUT AS #1
	065C	02D6	PRINT #1,FILES: 'save filename in default
		it file	
	066C	02D6	PRINT #1,NAMES: 'save the directory names
		as well	
	067C	02D6	CLOSE #1
	0683	02D6	
	0683	02D6	GOTO REDRAW
	0687	02D6	
	0687	02E6	SEARCH:
	068C	02D6	IZ = 1: 'set entry pointer
	0693	02D6	LOOP:
	0698	02D6	LINE INPUT #1,AS: 'read next pattern name from disk
	06A5	02D6	IF AS = NAMES THEN GOTO SEARCH.END: 'compare name with
		it's dir entry	
	06B8	02D6	IZ = IZ + 1
	06C1	02D6	IF IZ < (PATHUMI + 1) THEN GOTO LOOP: 'check for done
	06D4	02D6	SEARCH.END:

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Reagent Jet Printer  
Pattern Entry/Modification

Offset Data Source Line      IBM Personal Computer BASIC Compiler V2.00

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5        06E4 02D6  PATSAVE:
06E9 02D6      GOSUB ITEMBOIERASE:      'erase blue box around DIR
06EF 02D6      IF ELNUMI = 0 THEN GOTO FIRST: 'no elements in pattern
06FE 02D6      OPEN "PATDIR.RJP" FOR INPUT AS #1
10        070F 02D6      INPUT #1,PATHNUMI
0721 02D6      IF PATHNUMI < .80 THEN GOTO SAVE.PAT:      'directory full
              at 80 patterns
0730 02D6      CLOSE #1
0737 02D6      LOCATE 25,1:PRINT SPACE$(39):      'erase bottom 1
15        0734 02D6      in
              LOCATE 25,1:PRINT "Directory is full (80 patterns max)"*
;
076E 02D6      GOSUB ANYKEY:GOTO FIRST
0778 02D6  SAVE.PAT:
20        077D 02D6      GOSUB GETNAME: 'prompt for and get pattern name
0783 02D6      GOSUB SEARCH
0789 02D6      IF IZ > PATHNUMI THEN GOTO ADD.NEW.PATTERN
079A 02D6      LINE (1,1)-(318,189),0,BF:      'erase graphics tablet
07BF 02D6      LOCATE 10,13-(LEN(NAME$)/2):PRINT NAME$;" already exist
25        5.":      LOCATE 12,15:PRINT "Replace it?"
07F4 02D6      PATHNUMI = IZ
080E 02D6      AS = ""
0815 02D6      WHILE AS = ""
081F 02D6      AS = INKEY$:
30        082E 02D6      WEND
0838 02D6      IF AS = "Y" OR AS = ",," THEN GOTO SAVE.PATTERN
083B 02D6      GOTO FIRST
0844 02D6
0868 02D6
35        0868 02D6  ADD.NEW.PATTERN:
086D 02D6      KILL "PATDIR.CLD":      'delete old backup directory
0874 02D6      NAME "PATDIR.RJP" AS "PATDIR.OLD":      'save old direc
              tory
087E 02D6      OPEN "PATDIR.OLD" FOR INPUT AS #1
40        088F 02D6      OPEN "PATDIR.RJP" FOR OUTPUT AS #2:      'set up new dir
08A1 02D6      INPUT #1,PATHNUMI:      'read number of dir entries
08B3 02D6      PATHNUMI = PATHNUMI + 1: 'increase by 1
08B5 02D6      WRITE #2,PATHNUMI:      'save in new directory
08CD 02D6      FOR I=1 TO PATHNUMI - 1
45        08E6 02DA           LIKE INPUT #1,AS: 'read entry from old dir
08F3 02DA           PRINT #2,AS:      'write entry in new directory
0903 02DA           NEXT I
091E 02DA           PRINT #2,NAME$:      'write new entry to new directo
              ry
50        092E 02DA      CLOSE #1:CLOSE #2:      'done with directory
093C 02DA  SAVE.PATTERN:
0941 02DA      FILES = RIGHT$(STR$(PATHNUMI),LEN(STR$(PATHNUMI))-1) + "P
              AT.RJP"
0965 02DA      OPEN FILES FOR OUTPUT AS #1:      'create new pattern dat
              a file
55        0977 02DA      WRITE #1,ELNUMI:      'store number of elements
0988 02DA      WRITE #1,GRID:      'store grid dimension
0998 02DA      WRITE #1,REPEATI:      'store repeat count
09A9 02DA      WRITE #1,IOFF:      'store x axis offset for repeat

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20 Reagent Jet Printer PAGE 8  
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Offset Data Source Line IBM Personal Computer BASIC Compiler V2.00

25	09B9	023A	WRITE #1,YCFF: 'store y axis offset for repeat
	09C9	025A	FOR IZ = 0 TO ELEMJ1 - 1
	09D7	02DC	FOR JZ = 0 TO 5
	09DD	02CC	WRITE #1,SENDATZ(IZ,JZ); 'write screen a rray to file
30	0A03	025C	NEXT JZ
	0A10	022C	NEXT IZ
	0A22	02DC	CLOSE #1: 'done with data file
	0A29	02DC	OPEN "PAT52F.RJP" FOR OUTPUT AS #1
	0A38	02DC	PRINT #1,FILE\$: 'save filename in defau
35	0A46	02DC	lt file PRINT #1,NAMES\$: 'save the directory na me as well
	0A58	02DC	CLOSE #1
	0A62	02DC	GOTO FIRST
40	0A66	02DC	REM SPAGE

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I&M Personal Computer BASIC Compiler V2.00

0	02E0	PATCRAY:
10	02E3	GOSUB ITEMBOIERASE
	02E1	LINE (1,1)-(318,189),0,BF;
	02E6	'Erase graphics tablet
15	02E6	NEITEL:
	02E2	MESSAGE = 2
	02E5	GOSUB SETMENU
	02E8	
20	02E8	CX ITEM + 1 GOTO ALINE, RECT, SRECT, ACIRCLE, REDRAW, E
	02E0	ALINE:
	02E0	GOTJ NEITEL
	02E0	BACKUP:
25	02E0	GOSUB ITEMBOIERASE
	02E0	GOTO FIRST
	02E0	
30	02E0	ALINE:
	02E0	TEMP1 = 1
	02E0	STARTX\$ = "STARTING ENDPOINT"
	02E0	ENDX\$ = "ENDING ENDPOINT "
	02E0	GOTO ENTERELEMENT
	02E0	
35	02E0	RECT:
	02E0	TEMP1 = 2
	02E0	GOTO RECTMSG
	02E0	
40	02E0	SRECT:
	02E0	TEMP1 = 3
	02E0	RECTMSG:
	02E0	STARTX\$ = "STARTING CORNER"
	02E0	ENDX\$ = "ENDING CORNER "
	02E0	GOTO ENTERELEMENT
	02E0	
45	02E0	ACIRCLE:
	02E0	TEMP1 = 4
	02E0	STARTX\$ = "CENTER OF CIRCLE"
	02E0	ENDX\$ = "POINT ON CIRCLE "
	02E0	
50	02E0	ENTERELEMENT:
	02E0	GOSUB ITEMBOIERASE
	02E0	FLAG=0
	02E0	LOCATE 25,1:PRINT SPACE\$(39);
	02E0	LOCATE 25,1:PRINT STARTX\$;
	02E0	GOSUB DISPCURSOR
55	02E0	FINDSTART:
	02E0	GOSUB MOUSEACT
	02E0	IF AF = CHR\$(27) THEN GOTO ABORT
	02E0	IF AF = CHR\$(13) THEN GOTO SETSTART
	02E0	GOSUB CURSORMOVE
	02E0	GOTO FINDSTART
	02E0	
	02E0	ABORT:
	02E0	GOSUB PLACECURSOR
	02E0	GOTO NEITEL
	02E0	

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Reagent Jet Printer  
Pattern Entry/Modification

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75	Offset	Data	Source Line	TIEN Personal Computer BASIC Compiler V2.00
	0BF7	02EB	SETSTART:	
	0BFC	02EB	LOCATE 25,1:PRINT ENDNSER:	
	0C16	02EB	FLAG1 = TEAPI:III = XI:YII = YI	
20	0C2B	02EC	IF FLAG1 = 4 THEN PSET (III+4,YI+4)	
	0C35	02EC	FINDEXD:	
	0C5A	02EC	60SUB MOUSEACT	
	0C60	02EC	IF A\$ = CHR\$(27) THEN GOTO CANCELEL	
	0C77	02EC	IF A\$ = CHR\$(13) THEN GOTO SAVEEL	
25	0C8E	02EC	60SUB CURSORMOVE	
	0C94	02EC	GOTO FINDEXD	
	0C97	02EC	CANCELEL:	
	0C9C	02EC	60SUB PLACECURSOR	
	0CA2	02EC	ON FLAG1 60SUB ER1, ER2, ER3, ER4	
30	0CB3	02EC	FLAG1 = 0	
	0C9A	02EC	GOTO NEXTEL	
	0CBE	02EC	SAVEEL:	
	0CCE	02EC	60SUB PLACECURSOR	
35	0CC9	02EC	IF FLAG1 = 4 THEN CIRCLE (III+4,YI+4),SQR((XI-XII)^2+(YI-YII)^2),1	
	0D32	02EC	60SUB CORRECT	
	0D58	02EC	IF A\$="N" THEN GOTO REGRAN	
	0D4B	02EC	STOREEL:	
	0D50	02EC	SCNDATZ(ELNUM1,0) = FLAG1	
40	0D6A	02EC	SCNDATZ(ELNUM1,1) = III	
	0D85	02EC	SCNDATZ(ELNUM1,2) = YII	
	0DA0	02EC	SCNDATZ(ELNUM1,3) = XI	
	0DBB	02EC	SCNDATZ(ELNUM1,4) = YC	
	0DD6	02EC	SCNDATZ(ELNUM1,5) = 0	
45	0DEF	02EC	ELNUM1 = ELNUM1 + 1	
	0DF8	02EC	FLAG1 = 0	
	0DFF	02EC	GOTO NEXTEL	
	0E03	02EC	REM SPAGE	

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6      0E03 02EC  REDRAW:
0E08 02EC  GOSUB ITEMBOIERASE
0E0E 02EC  LINE(1,1)-(318,189),0,BF
0E33 02EC  IF ELNUM1 = 0 THEN GOTO NEITEL
10     0E42 02EC  FOR I=0 TO ELNUM2-1
0E42 02EC  ON SCRDATI(I,0) GOSUB RD1, RD2, RD3, RD4
0E81 02F0  NEXT I
0E9C 02F0  GOTO NEITEL
15     0E90 02F0
0E90 02F0  **** Sub-routines called by main module ****
0E90 02F0
0E90 02F0  SUBMENU:
0E95 02F0
20     0E95 02F0  LOCATE 25,1:PRINT SPACE$(39);
0EC2 02F0  ON MENUH1 GOSUB MENU1, MENU2
0ED1 02F0
0ED1 02F0  FOR I=0 TO 6
0EDB 02F0  READ MENU5(I)
25     0EF2 02F0  LOCATE 25,(I*6)+2:PRINT MENU5(I);
0F2B 02F0  NEXT I
0F46 02F0
0F46 02F0  READ MAXITEM
0F4D 02F4  ITEM = 0
30     0F57 02F4
0F57 02F4  NEWITEM:
0F5C 02F4  GOSUB NEWITEMBOX
0F62 02F4
0F62 02F4  NEITITEM:
35     0F67 02F4  GOSUB ITEMSEARCH
0F6D 02F4  IF AS = CHR$(13) THEN RETURN: ITEM has correct value
0FB4 02F4  IF LEN(AS) < 2 THEN BEEP:GOTO NEITITEM
0F9A 02F4  IF ASC(MIDS$(AS,2,1)) = 75 THEN GOTO LEFTAR
0FB6 02F4  IF ASC(MIDS$(AS,2,1)) = 77 THEN GOTO RIGHTAR
40     0FD2 02F4  BEEP:GOTO NEITITEM
0FD9 02F4
45     0FD9 02F4  LEFTAR:
0FDE 02F4  IF ITEM = 0 THEN GOTO NEITITEM
0FEE 02F4  GOSUB ITEMBOIERASE
0FF4 02F4  ITEM = ITEM - 1
1003 02F4  GOTO NEWITEM
1007 02F4
1007 02F4  RIGHTAR:
100C 02F4  IF ITEM = MAXITEM THEN GOTO NEITITEM
50     101F 02F4  GOSUB ITEMBOIERASE
1025 02F4  ITEM = ITEM + 1
1034 02F4  GOTO NEWITEM
103B 02F4
103B 02F4  MENU1:
103D 02F4  RESTORE MN1
1044 02F4  RETURN
1048 02F4
1048 02F4  MENU2:
104D 02F4  RESTORE MN2

```